



Femtosecond Synchronization of Large Scale FELs – Achievement, Limitations and Mitigation Paths –

FLS 2023 talk extended version

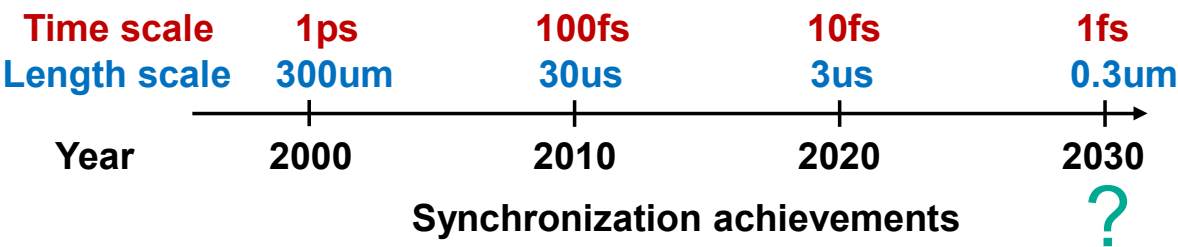
Holger Schlarb on behalf of the LbSync, Special Diag. and LLRF team at DESY
Darmstadt, BRD, 28th of June 2024

- **Introduction**
- **Why precision synchronization & Sources of timing jitter**
- **Optical synchronization – achievements / limits / mitigations**
- **Conclusion**

Introduction

Introduction

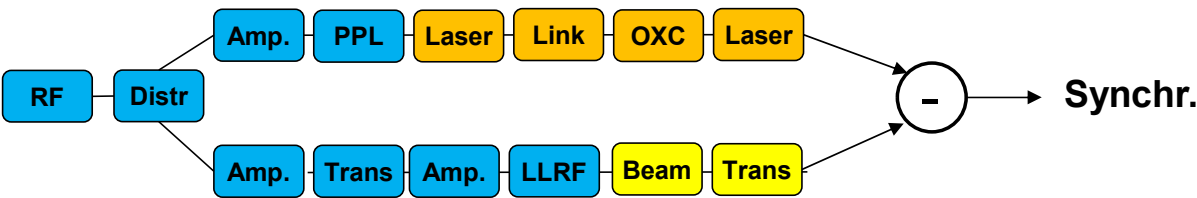
Time & length scales:



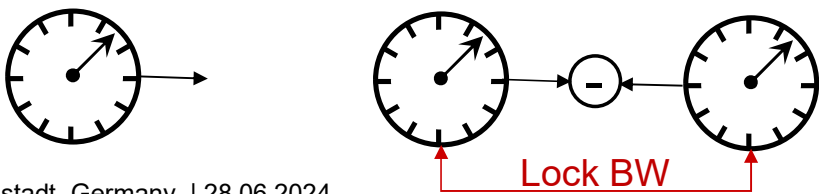
Duration matters!

Short range	1us ... 1ms:	PS, EMI, Electronics, Material Prop., ...
Mid range	1ms ... 10s:	Acoustic, Seismic, Air/Water flow, Fans, ...
Long range	10s ... days:	Thermal, Humidity, Air Pressure,...

Long chains of devices:



Absolute & relative timing jitter:

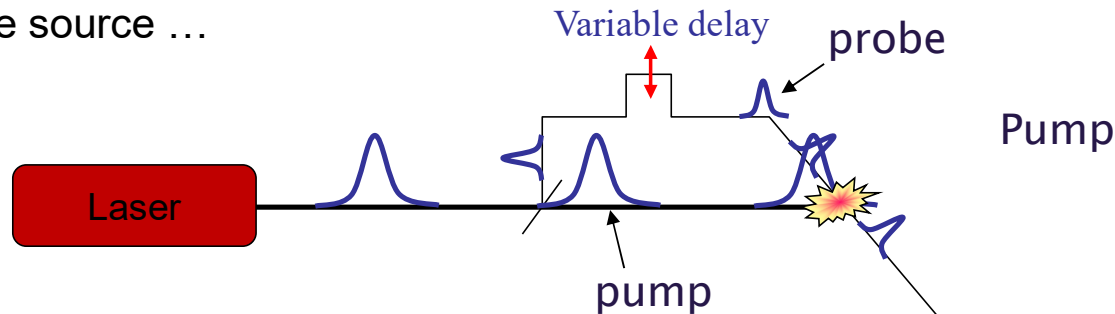


Why precision Synchronization? & Source of timing jitter

Source of timing jitter for FELs

Pump-probe experiments

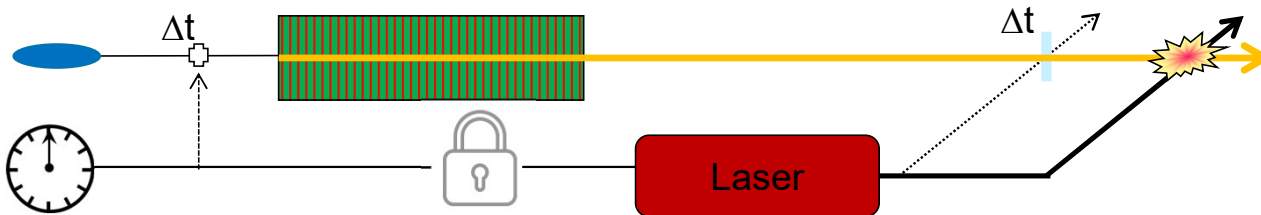
- Same source ...



Probe = flash



- FELs: disjunction source



Shot pulses fs ← ps

Precision: depends on experiment
Ideally: jitter < pulse durations

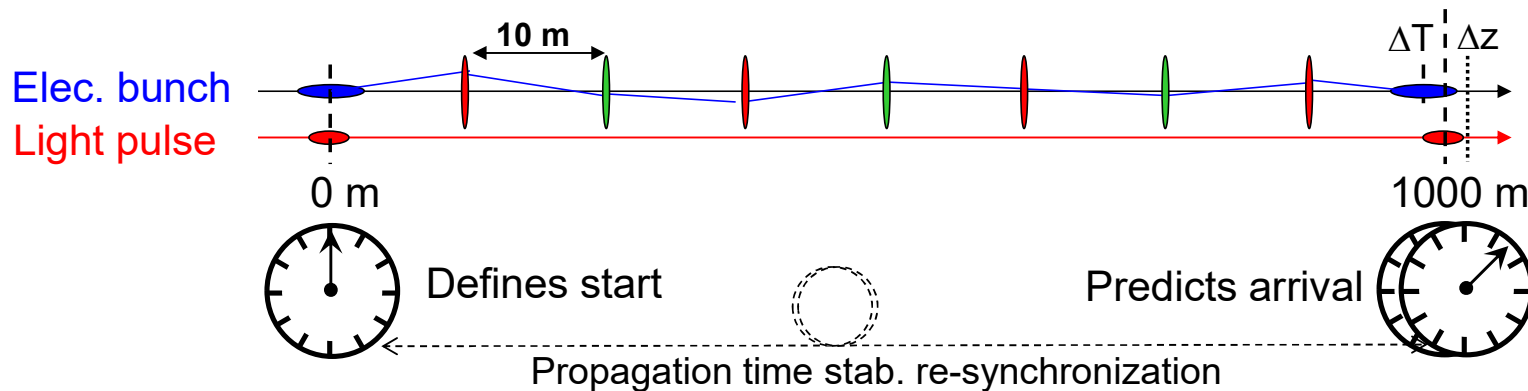
But: post-sorting often also possible!

- Post-sorting become problematic if:

- Special timing requirements in experiment
- 3rd independent source involved
(laser → e⁻ mani. / e⁻ driven THz source / ...)
- Low interaction rates / cross-sections
(HIBEF / dilute targets / aver. detectors)

Source of timing jitter for FELs

Straight sections ... energy ... ground motion



Lorentz factor $\gamma = E/m_0c^2$

$E = 1 \text{ GeV}$

$$\beta \approx 1 - \frac{1}{2\gamma^2} = 0.999999869$$

$\Delta T = 435 \text{ fs}$

Energy jitter: $\delta E/E < 0.1\%$ $\rightarrow$ $\delta t < 0.8 \text{ fs}$ 😊

Orbit deviation: $\delta x < 50 \mu\text{m}$ $\rightarrow$ $\delta t < 0.04 \text{ fs}$ 😊

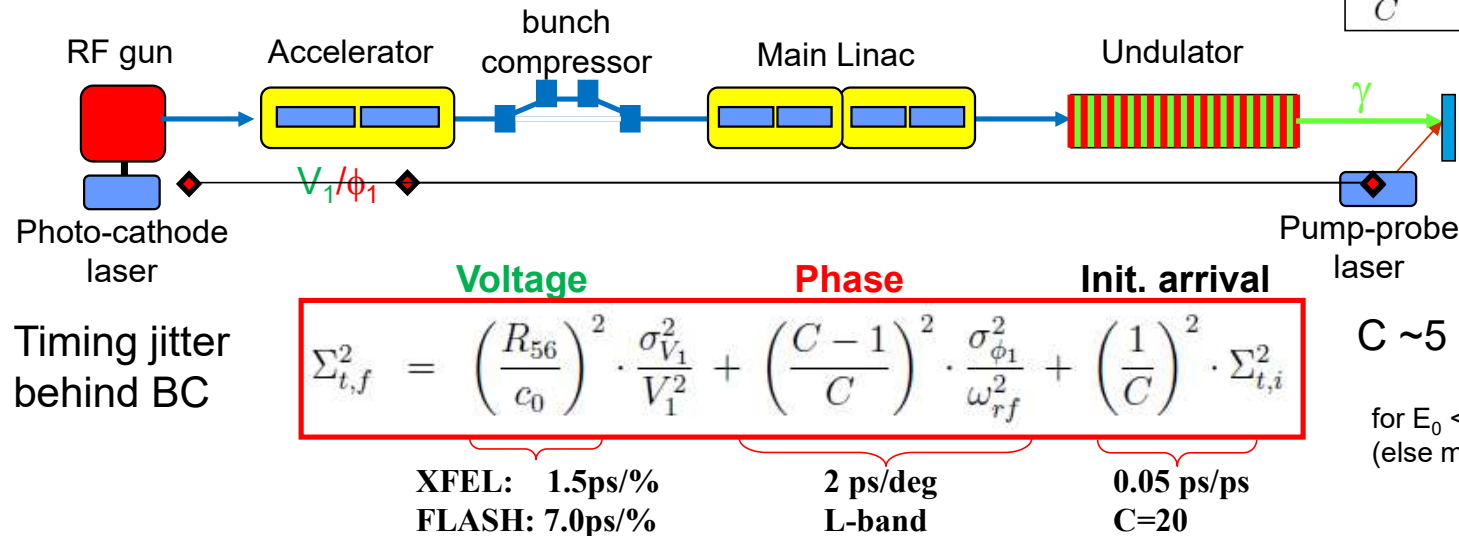
Vibration: $\delta z \sim \text{few } 100 \text{ nm}$ $\rightarrow$ $\delta t < 1 \text{ fs}$ 😐

Ground motion/relocations: $\delta z \sim \dots 10 \mu\text{m}$ $\rightarrow$ $\delta t \sim \dots 30 \text{ fs}$ 😞 (slow, may predictable...)

Source of timing jitter for accelerators / FELs

Magnetic e-bunch compression impacts:

a) RF acc. fields defines arrival



Compression factor C:

$$\frac{1}{C} = \frac{\partial s_f}{\partial s_i} \Rightarrow C_1 = \frac{1}{1 - R_{56}\delta'(0)}$$

C ~5 ... 20 typically

for $E_0 \ll E_1$ and $E_0' \ll E_1'$
 (else more distributed across stations)

b) RF acc. fields large impact on longitudinal phase space

$$\frac{\delta C}{C_1} = -\overbrace{(C_1 - 1)}^{3 \dots 6} \left[\left(3 \tan(\phi_1) + \frac{1}{\tan(\phi_1)} \right) (\delta\phi_1 - \omega_{RF}\delta t_{ini}) + 4 \frac{\delta V_1}{V_1} \right]$$

Tolerance $\propto$ **Compression** **Phase & Init. arrival** **Voltage**

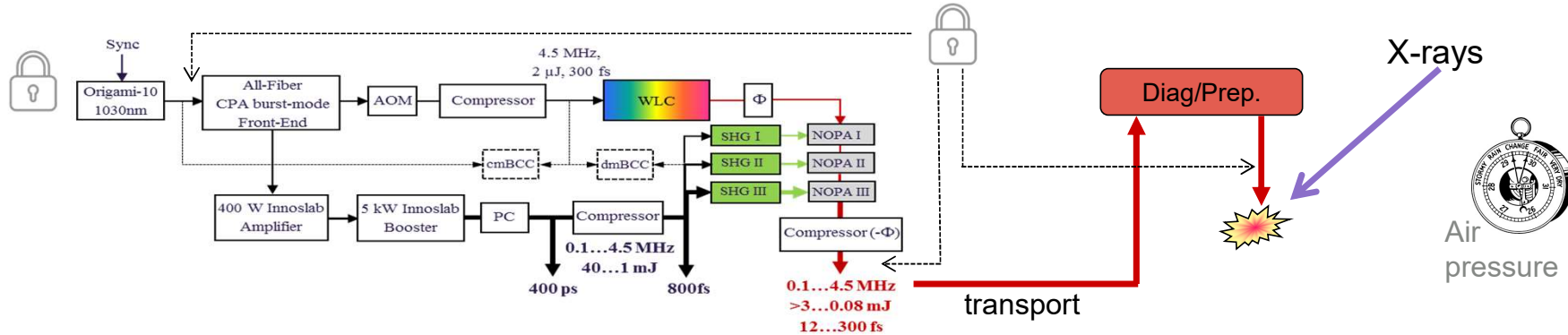
Conclusions:

- Use multiple compressors
- RF field control is critical
- RF reference vs PP-laser closely locked

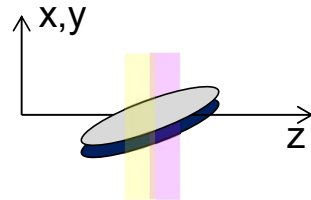
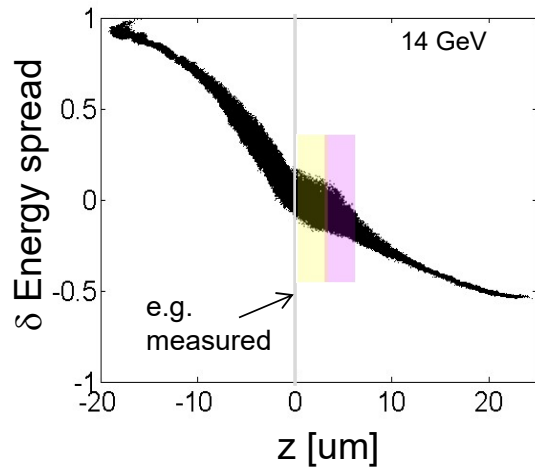
Source of timing jitter for FELs

Additional time jitter sources ...

- Laser systems**



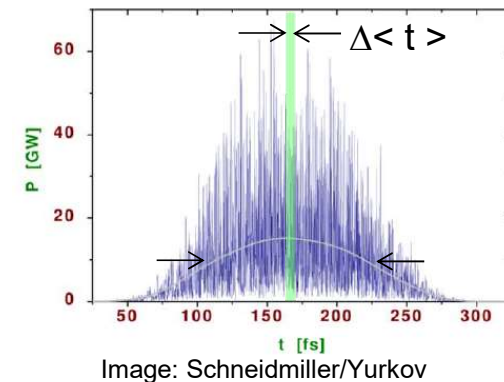
- Spatial - longitudinally distortion in electron beam**



Remark:

- Mode & setting of accelerator critically influences timing jitter

- SASE fluctuations**



$\Delta < t > \sim$ pulse width σ_t
 $\Delta < t > \sim 1/M$ (or $1/\lambda_{ph}$)
 will depend on saturation
 (tails start to lase...)

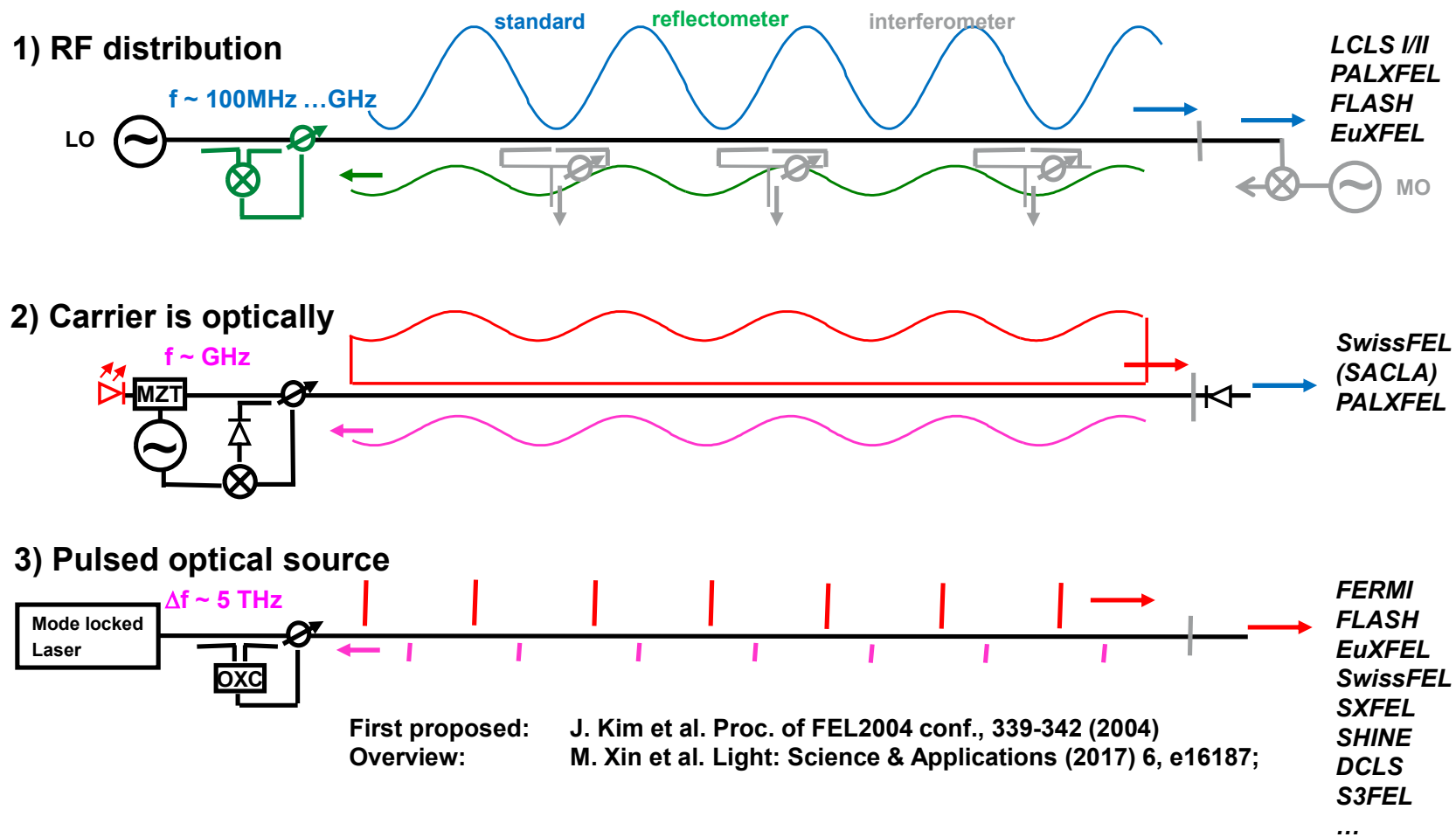
EuXFEL ~ 0.3 fs

Optical Synchronization System at European XFEL

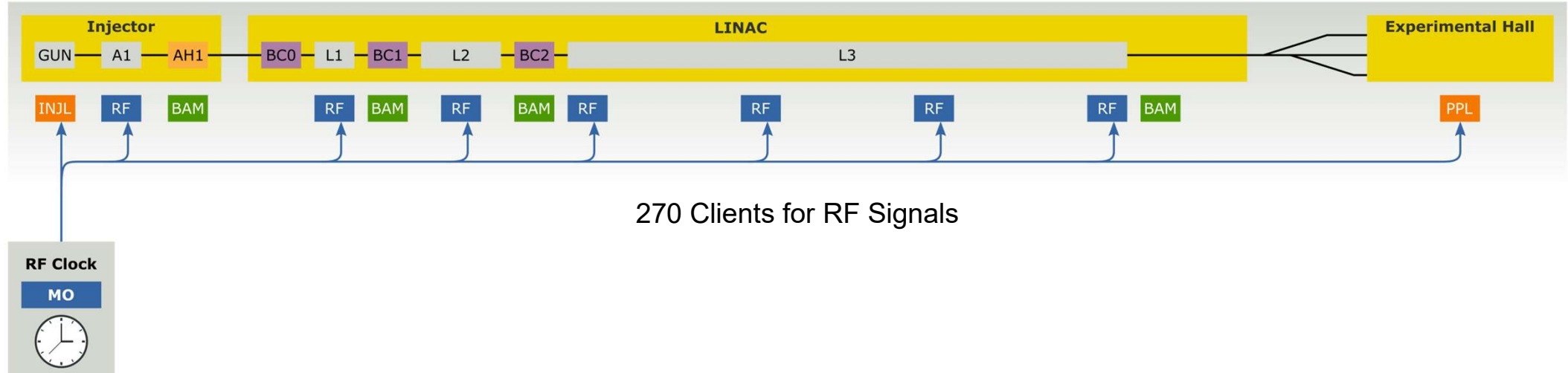
Different synchronization approaches

Various approaches:

$$\frac{\Delta t}{t} = \frac{\Delta f}{f}$$



Optical Synchronization System at EuXFEL



World-wide Unique Large-Scale 24/7 Operation

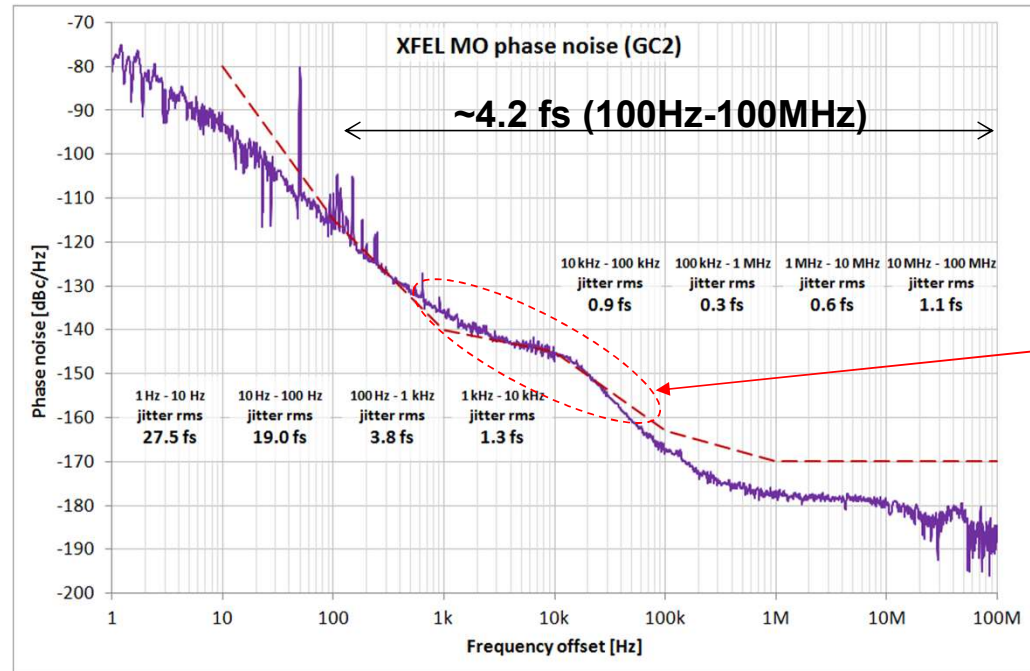
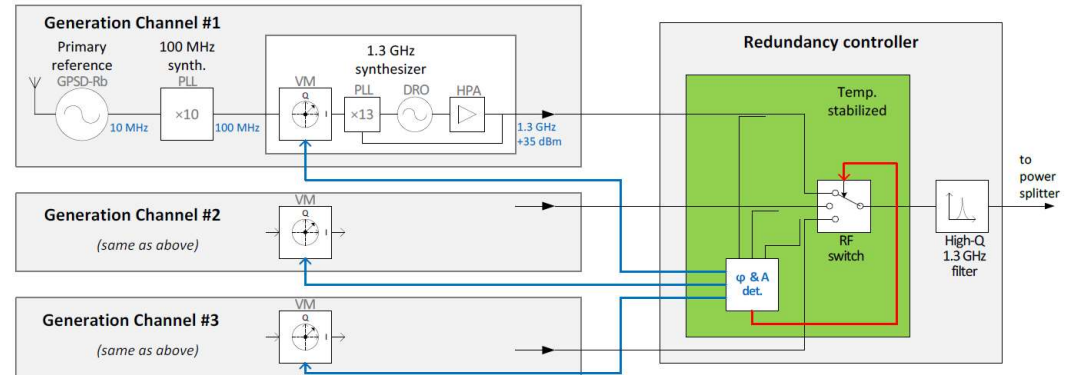


- **Laser locking** (injector, pump-probe, ...)
- RF re-synchronization (**REFM-OPT**)
- Bunch Arrival time Monitors (**BAM**)
- Laser-pulse Arrival time Monitors (**LAM**)

RF Main Oscillator (MO)

Design

- phase stability of 10^{-11} by locking to GPS
- 100 MHz OCXO
- 1.3 GHz DRO
- 24/7 operation, 3 redundant setups



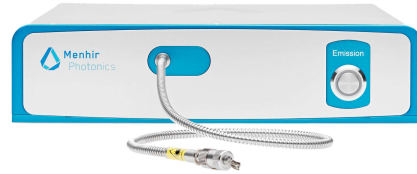
Phase noise (&bump) caused residual error in MO - MLO Lock (~2-3 fs)

Main Laser Oscillator (MLO)

The Main Optical Reference

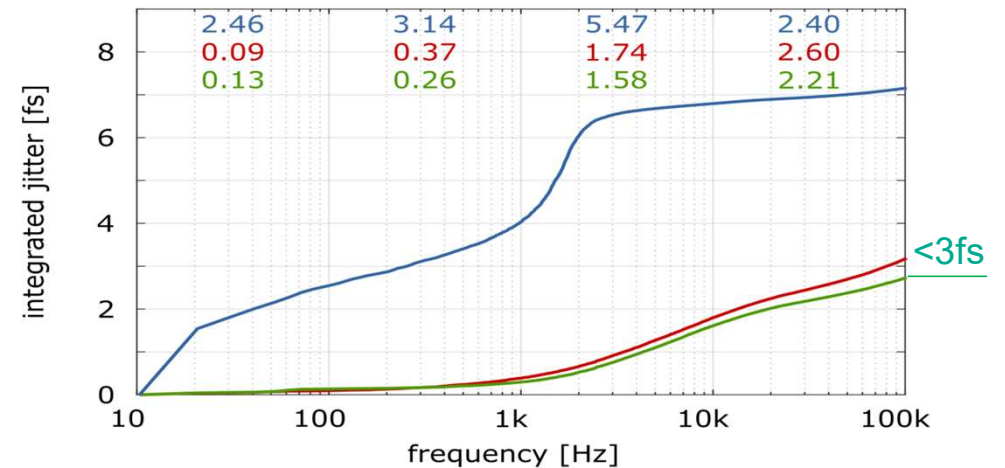
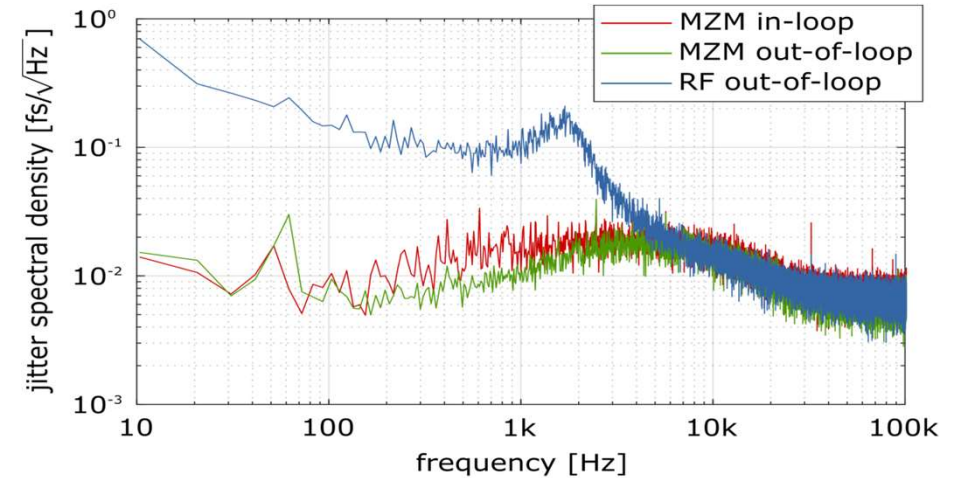
Oscillator

- commercial osc.
- **216 MHz** → 1.3 GHz / 6
- Ultra-low phase noise, 1550 nm
- **24/7 operation**
- 2 MLO installed for redundancy, fast switching



Laser-to-RF synchronization

- Locked to RF MO
 - amplitude insensitive locking scheme
- Low-noise (**~3 fs rms**)
- Low-drift (**< 2 fs pkpk, 1 week**, out-of-loop MZM)



Courtesy: T. Lamb

Free-Space Distribution

Laser Beam Distribution for 24 Fiber Link Stabilization Units

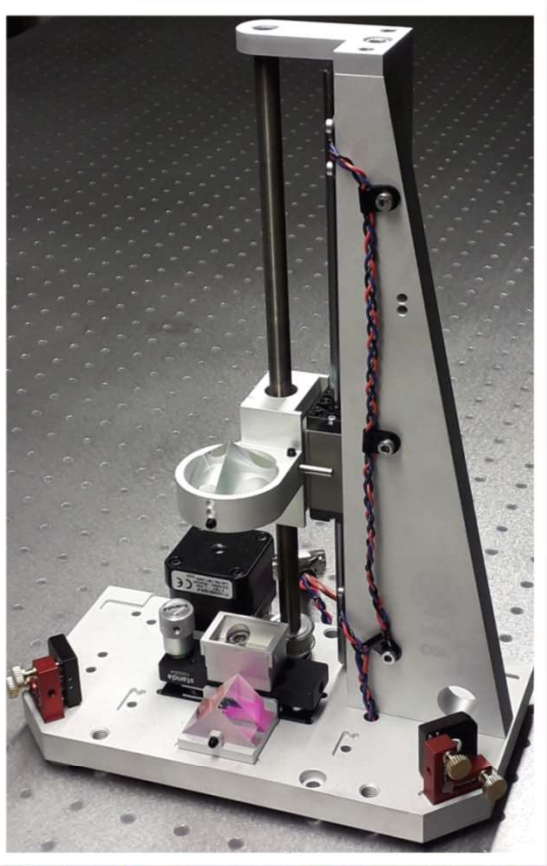
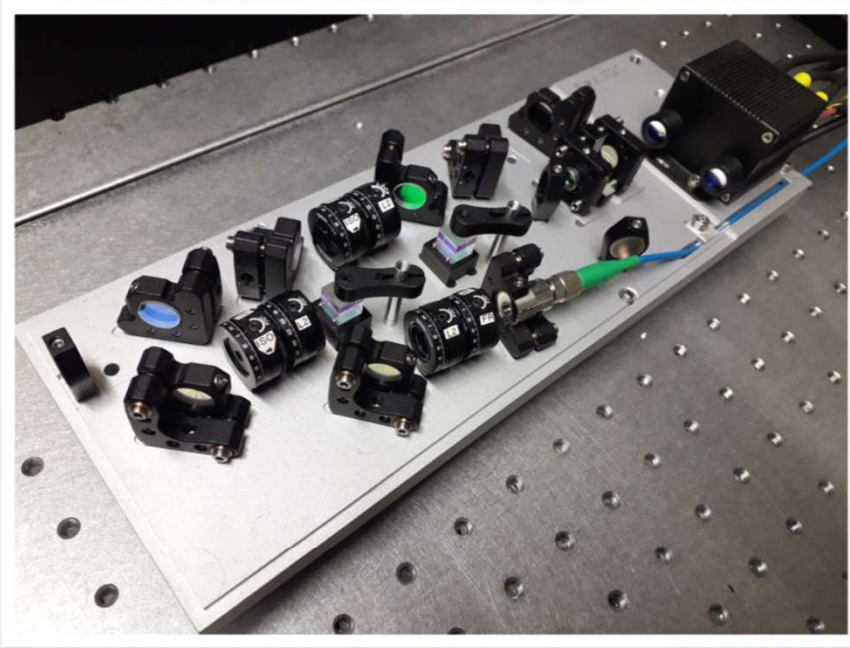
- **SuperInvar** optical table
 - thermal expansion coefficient ~ 1 fs/m/K
 - table covered and environmentally stable
 - $\ll 0.1$ K temperature stability
 - < 1 % RH pkpk
- Space for **24 link stabilization units**
 - identical path lengths, symmetric setup
- 8 fiber links with **4 ns optical delay stage**
 - arbitrary timing possible for BAM operation



Courtesy: J. Mueller

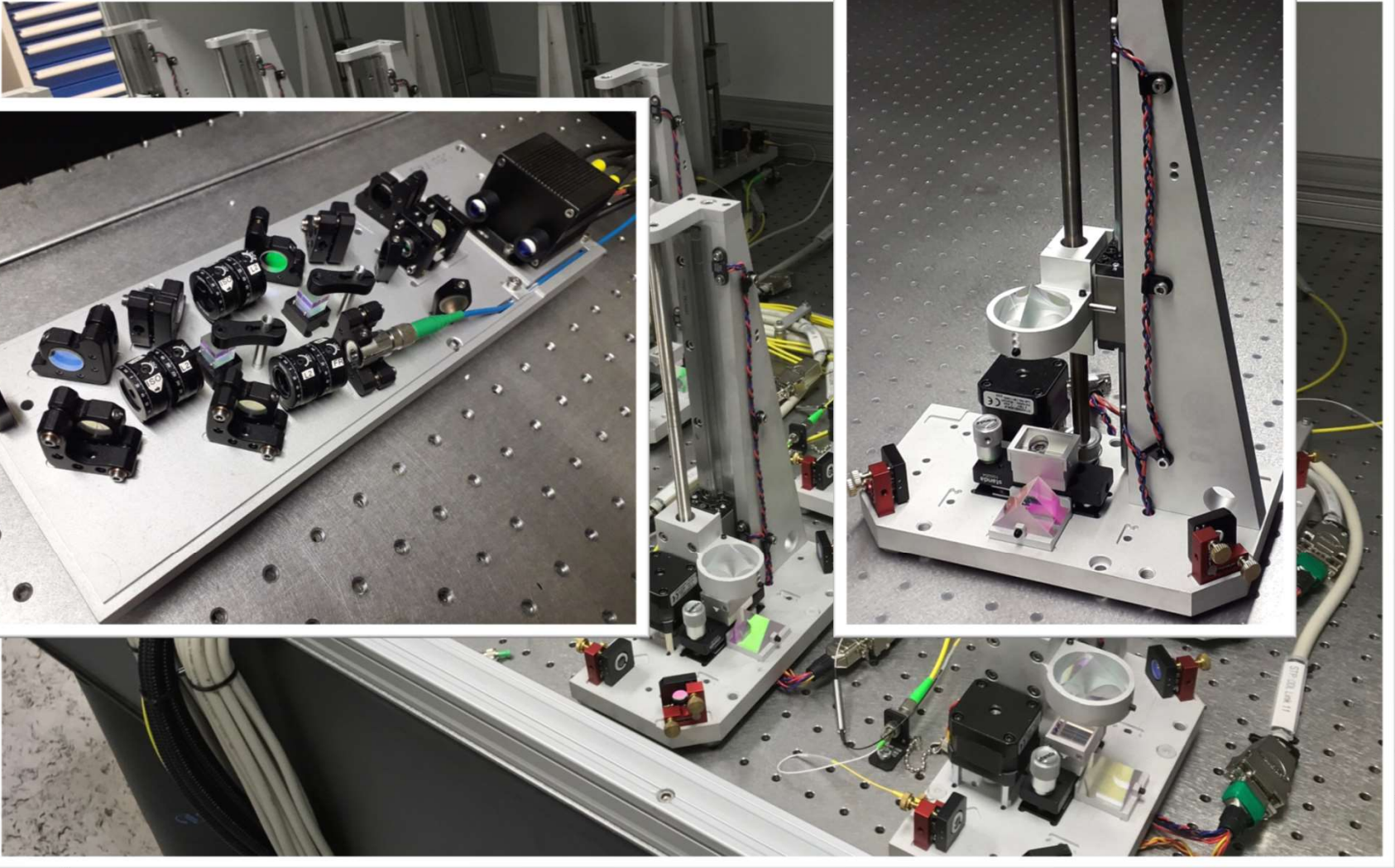
Link Synchronization

Measurement



timing error

- base
- inser
- typic



tion

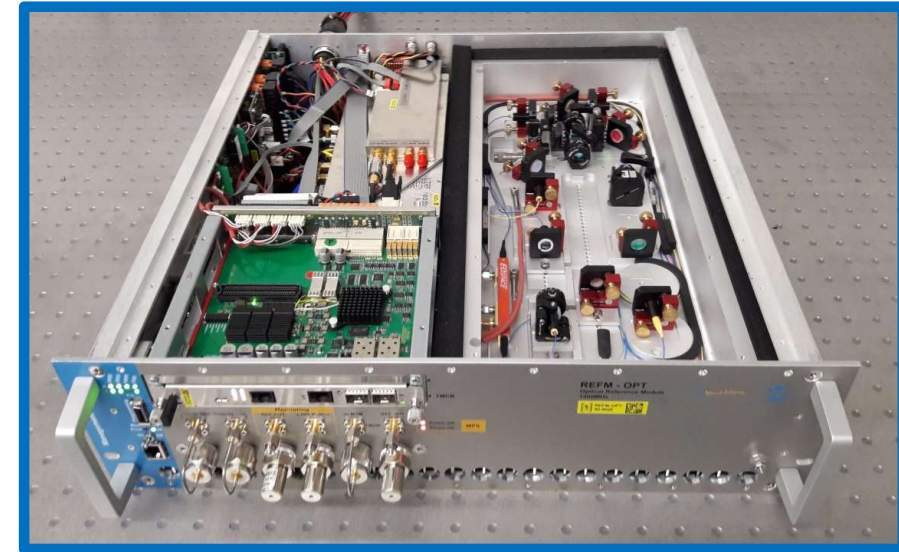
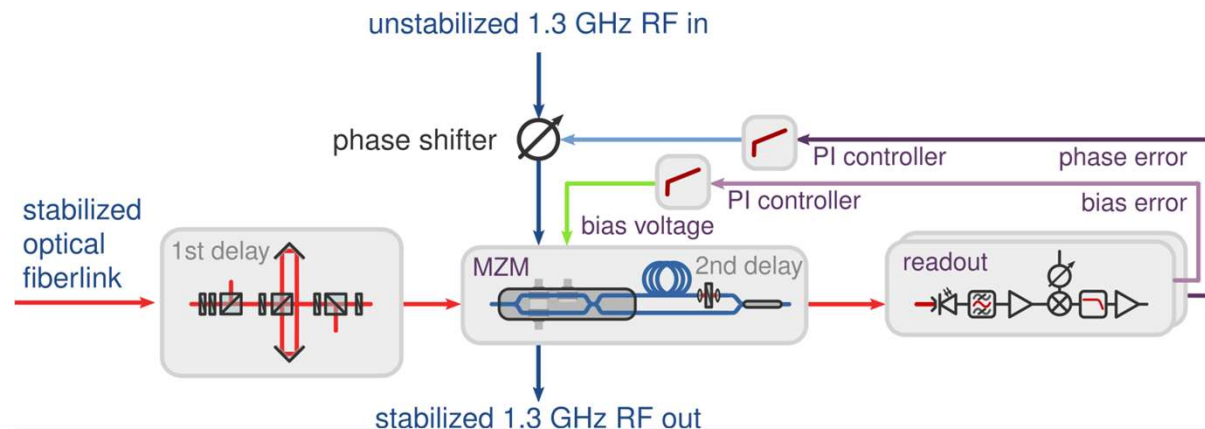
, fast)
f-built

Courtesy: J. Mueller

The Optical Reference Module (REFM-OPT)

Femtosecond RF Reference Phase Stabilisation

- Employs a **drift-free laser-to-RF phase detector**
- Locally re-synchronizes the 1.3 GHz RF reference with **femtosecond precision** in a PLL
- 1st delay line → RF sampled at 0° and 180°
- 2nd delay line → increase SNR + phase/bias feedback
- Sophisticated **exception handling**



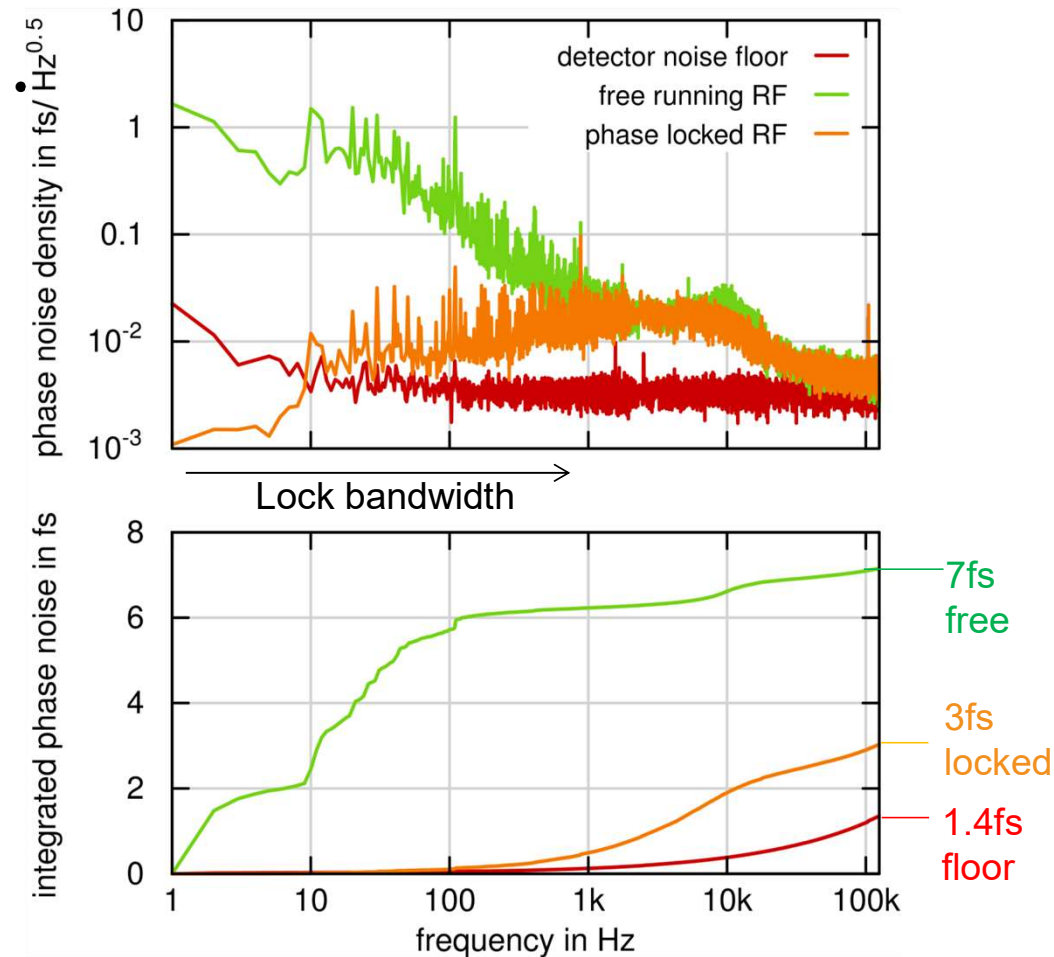
engineering

- **fully integrated** stand-alone 19" module
- temperature and humidity stabilized optical compartment

Courtesy: T. Lamb

The Optical Reference Module (REFM-OPT)

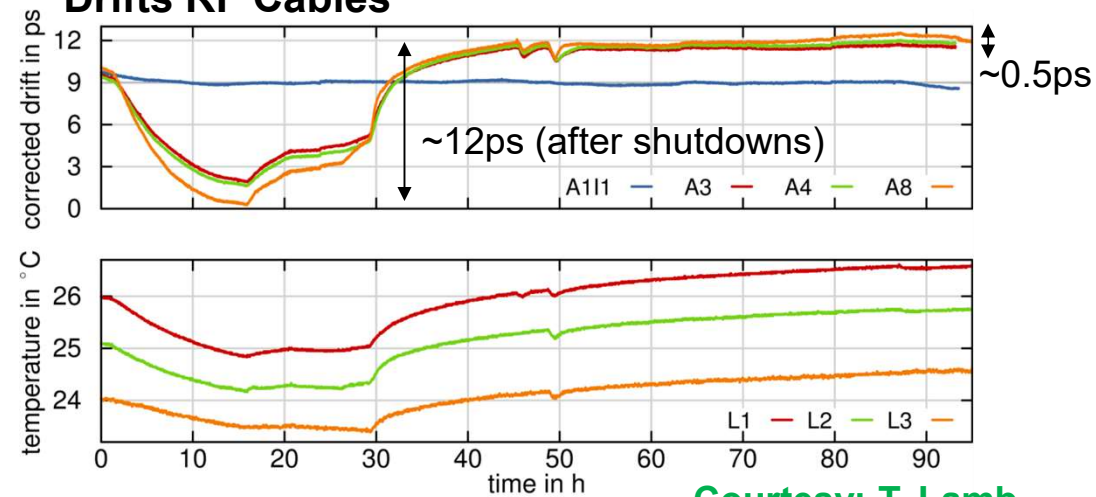
Femtosecond RF Reference Phase Stabilisation



Measurement Bandwidth 1 Hz to 125 kHz

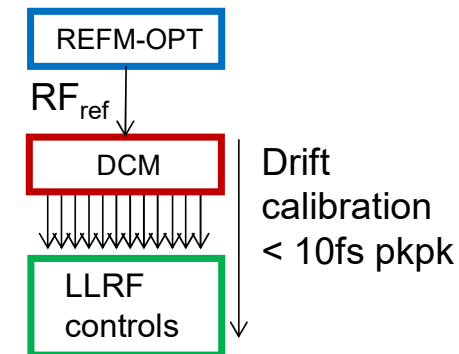
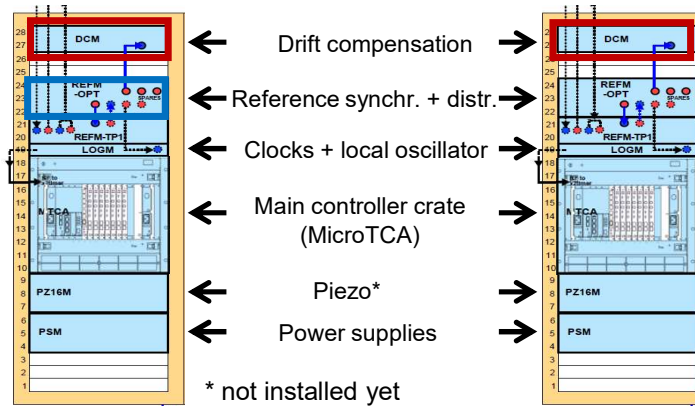
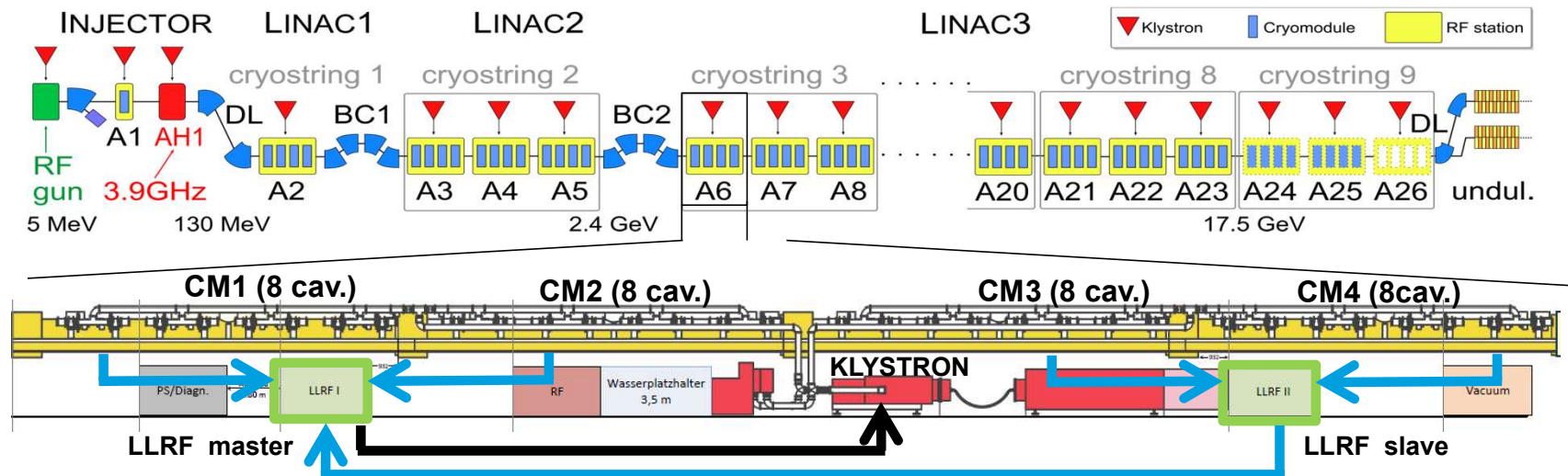
- K_ϕ of 3.1 V/ps
- integrated detector noise floor 1.4 fs (red)
- unlocked RF integrated jitter 7.2 fs (green)
- locked RF integrated jitter 3.0 fs (orange)

Drifts RF Cables



Courtesy: T. Lamb

Precision RF controls

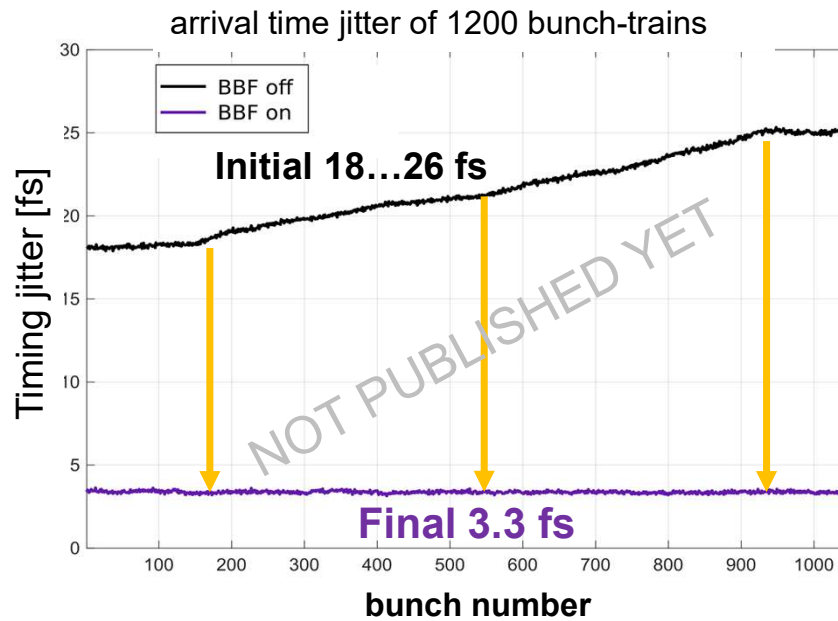
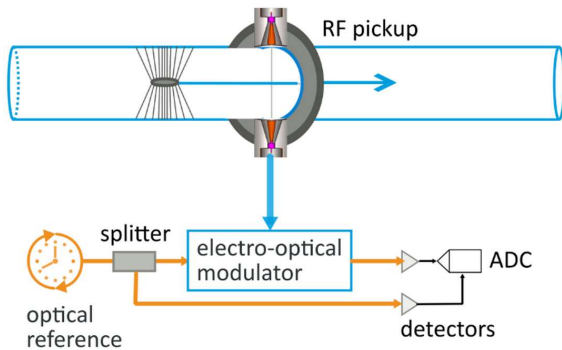
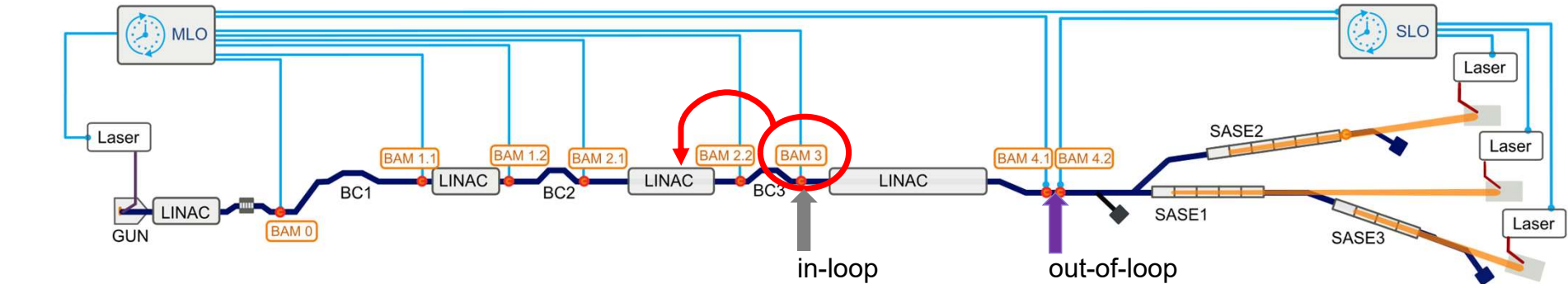


More than 3000 RF channels
Requirements: $<0.01\text{deg}$ and $<0.01\%$

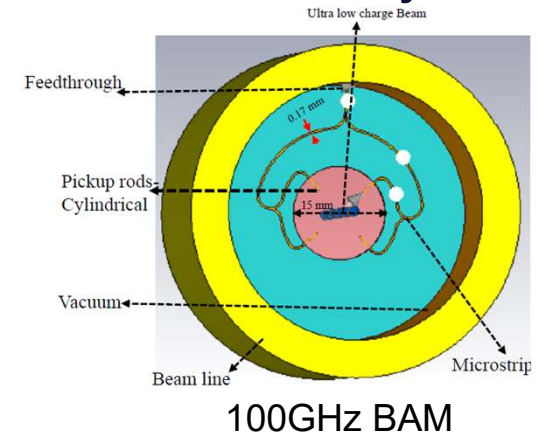
Courtesy J. Branlard

New world record arrival stability

Intra-burst arrival-time stability better than 4fs rms



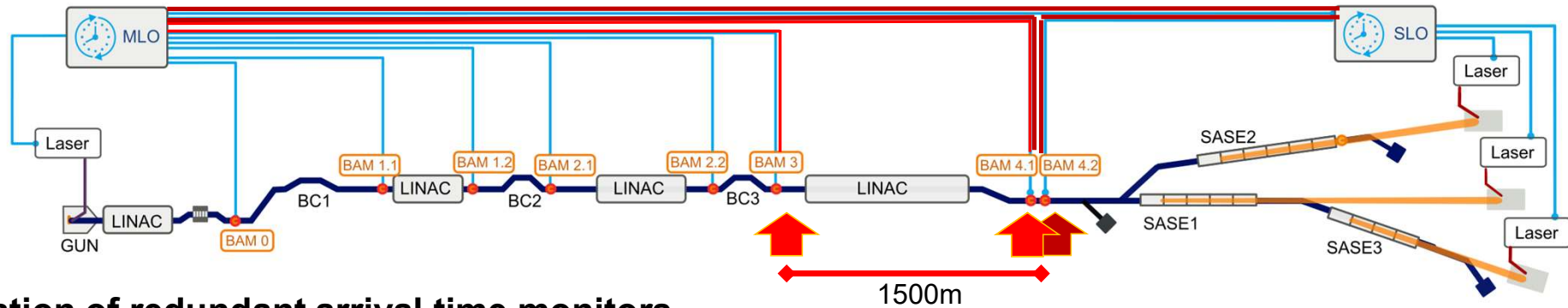
Goal: 1 fs next years



Facility	Best	Daily
EuXFEL	3.3 fs	~ 4...5 fs
FLASH	4.7 fs	~ 6 fs

Evaluation of synchronization system performance

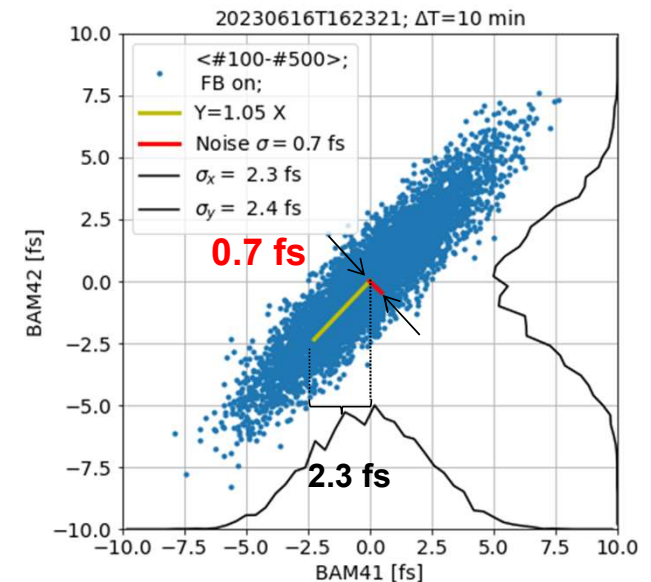
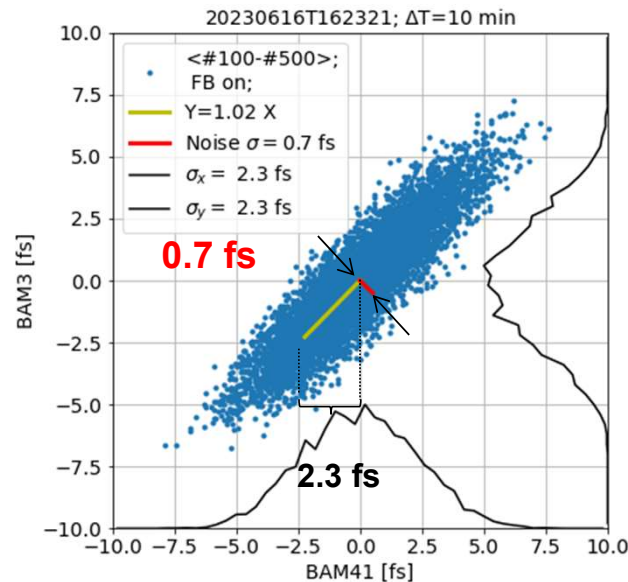
Long-range synchronized links add only 700as residual noise



Correlation of redundant arrival time monitors

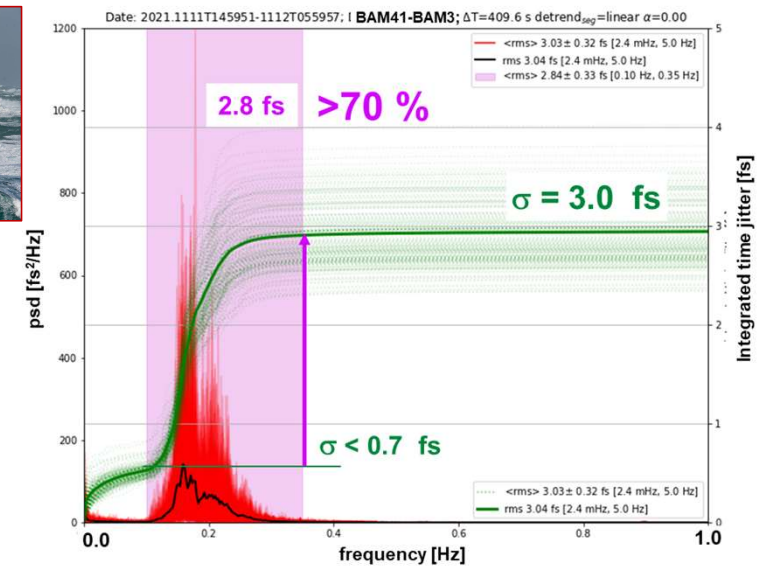
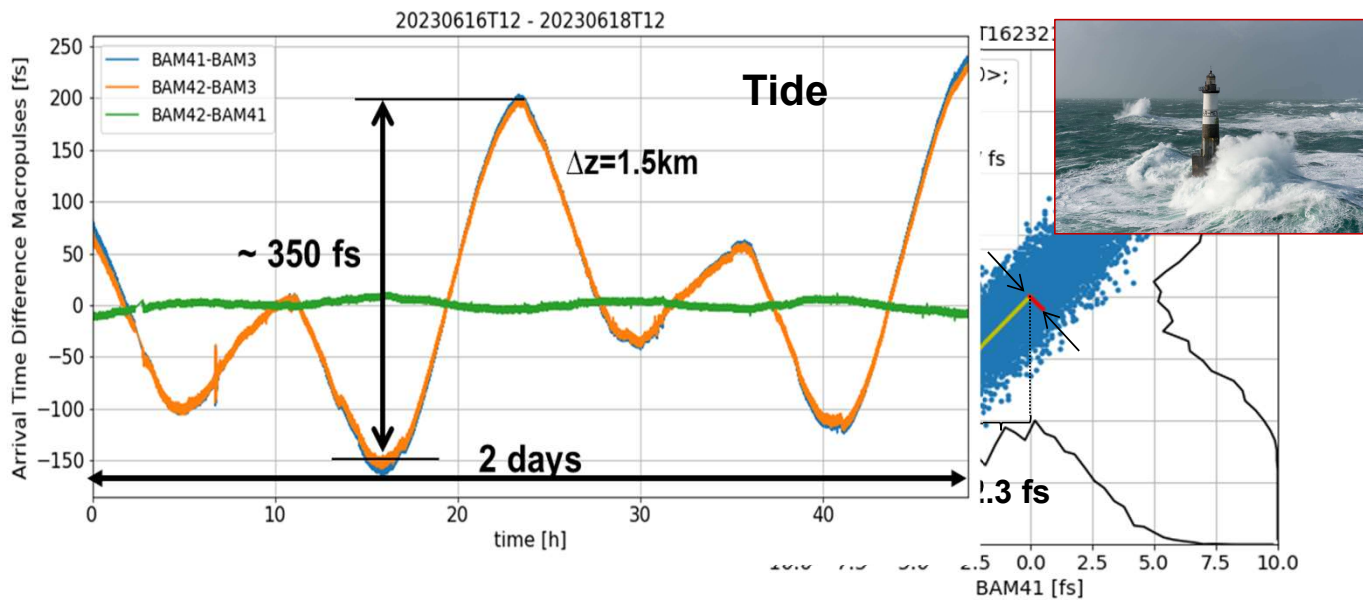
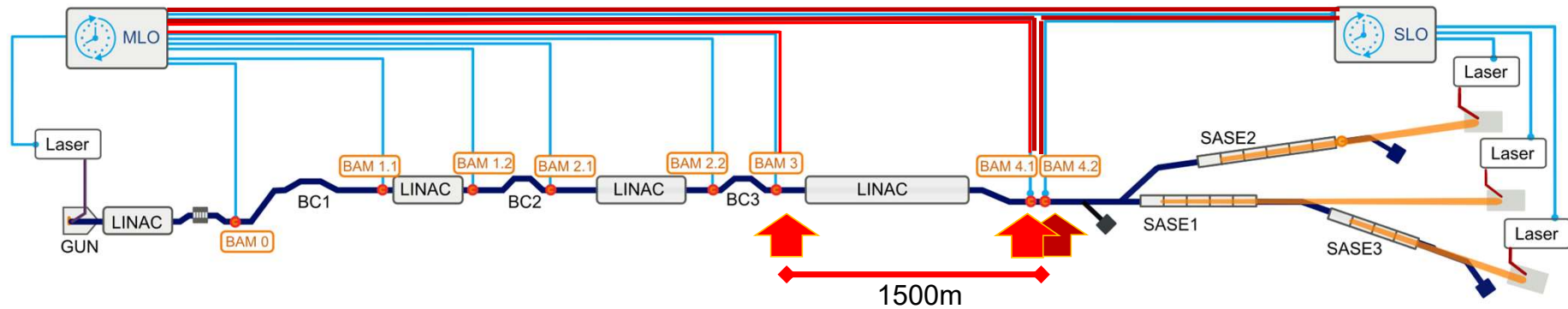
10 min. (6000 trains)
mean(400 bunches)

- Remove BAM high-freq. instr. noise
- Residual jitter of macro-pulses
- Uncorrelated noise
= stability of optical reference



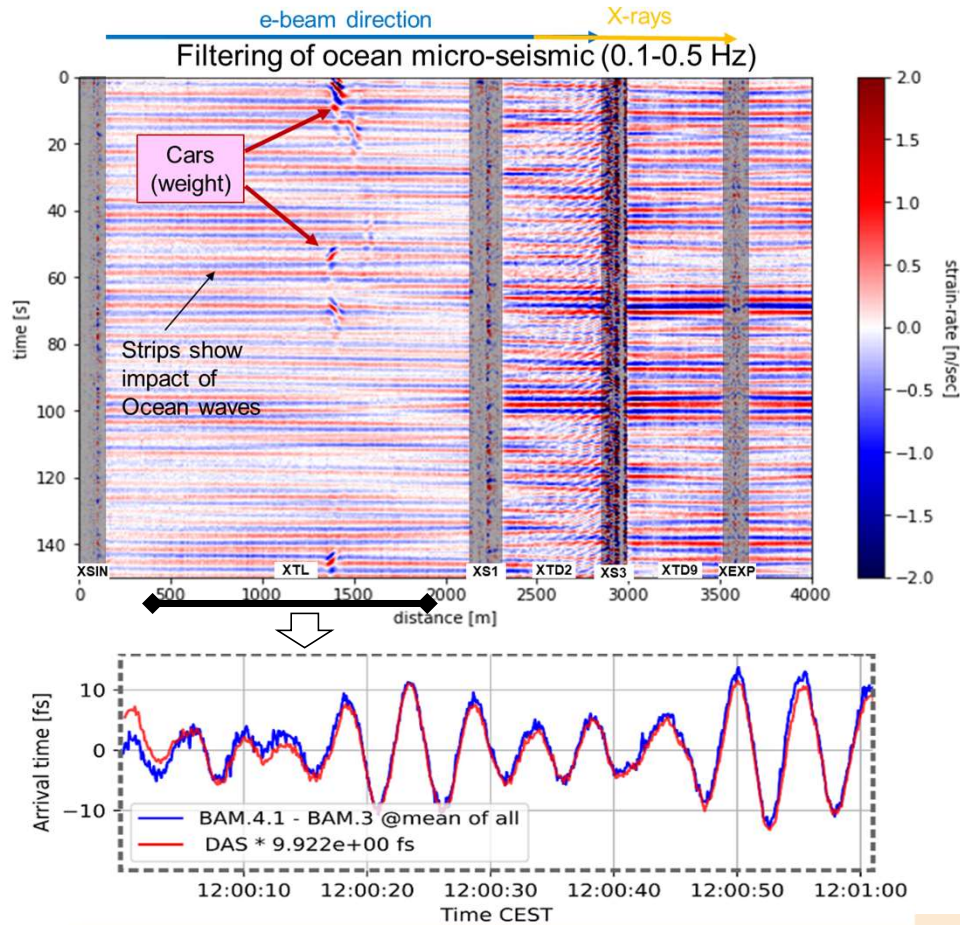
Tide & micro-seismic

Synchronisation

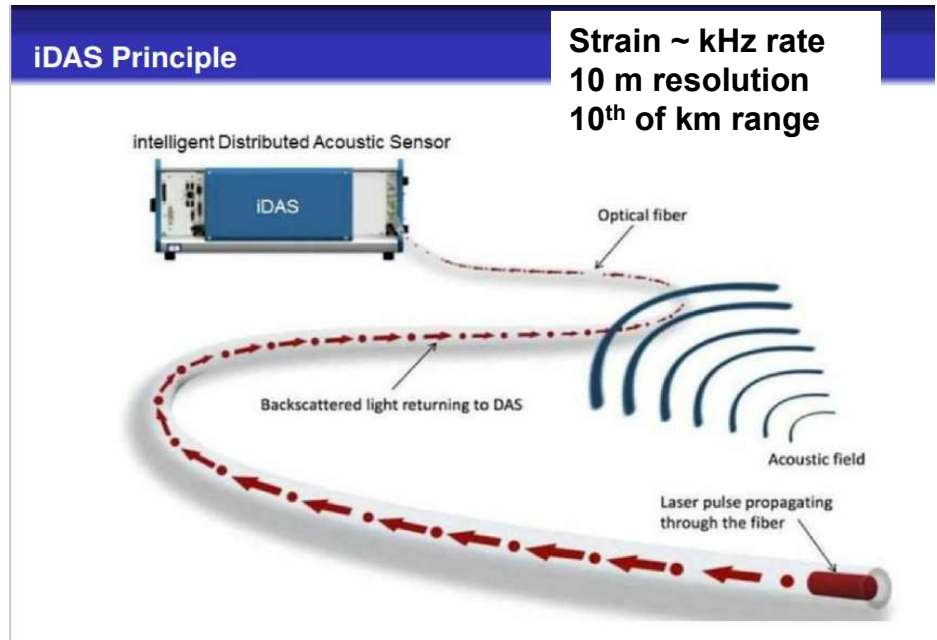


Mitigation of micro-seismic

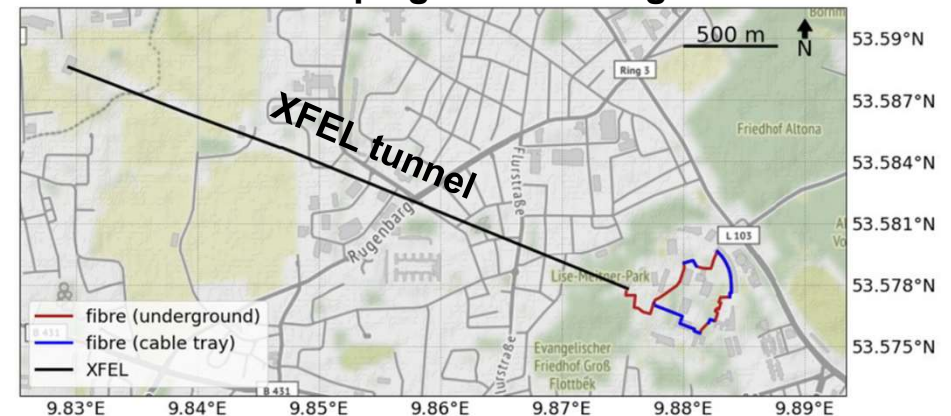
Using distributed fiber optical sensing (DOFS) ...



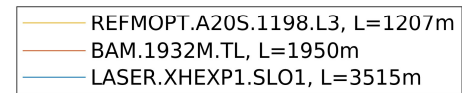
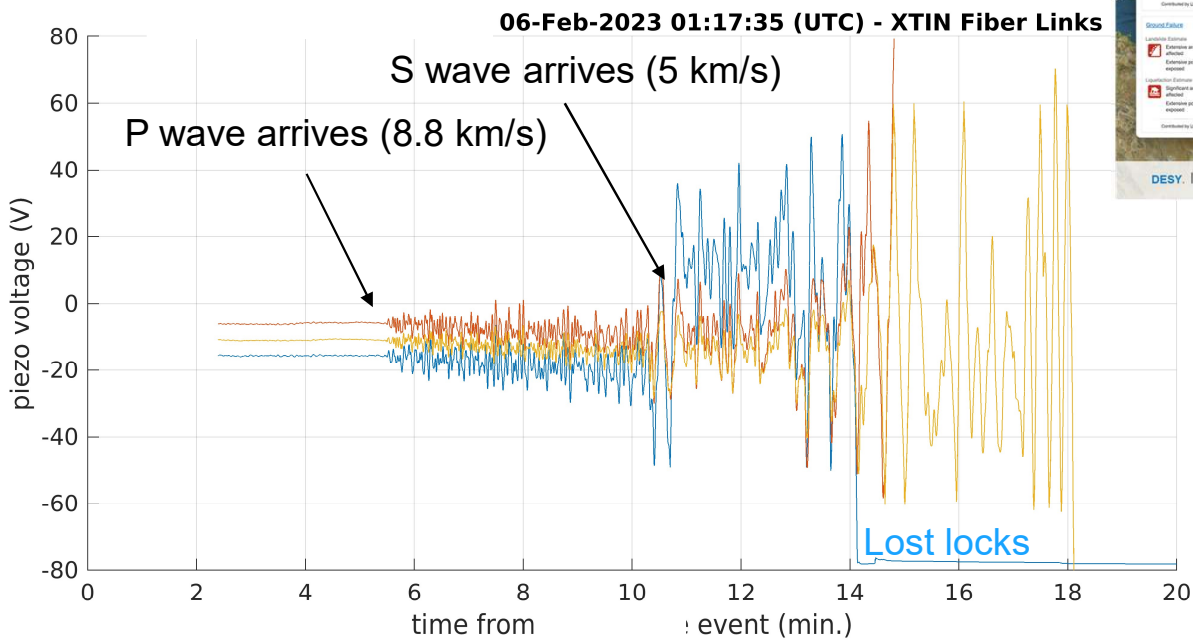
Mitigation path: predict impact of ocean wave



Measurement campaign 12.6 m length



Failed link length compensation ...



From analysis → EuXFEL > 3 mm stretched!
Event was visible > 1 h

DESY. Holger Schlarb | Femtosecond Synchronization of Large Scale FELs | TEMF, Darmstadt, Germany | 28.06.2024

Conclusion & Outlook

Control jitter and drifts of pump-probe lasers..

- Features can be resolved with resolutions of < 100 as
- Stability optical reference system [mHz...kHz] < 700 as
- Electron beam stabilization ~ 4 fs → next gen BAMs ~ 1 fs
- Impact of ocean waves (in winter) ~ 2 fs/km → DOFS
- Pump-laser system jitter ~ 10-20 fs → LAM / fast-FB
- Drifts of optical reference system ~ 20 fs pkpk → tbd.
- Tide effects ~ 150 fs/km → add. meas.

- ~1 fs stability MHz – mHz seems feasible, but controlling drifts will be tough!
- Microstructure for as pulse generation → Photon Arrival Monitoring increased relevance

Thanks for attention

Acknowledgement:

J. Branlard, L. Butkowski, A.-L. Calendron, M. Czwalinna, M. Felber, J. Georg, B. Lautenschlager, T.Lamb, M. Killenberg, T. Kozak, F. Ludwig, U. Mavric, J. Müller, D. Rothe, S. Pfeiffer, H. Pryscheleski, Ch. Schmidt, S. Schulz, S. Sydlo, E. Schneidmiller, M. Yurkov, ...
SPM/SFX-team, FXE-team, Beam Dynamics team,
and many more...

What gives me headache

Potential limitations e.g. in LLRF Systems

Short recap:

- $R56 \sim 30\text{mm}$ @ 1fs stab. $\rightarrow dA/A \sim 1e-5$ (or better)
- Frequently observe beam stability worse than predicted by field measurements
- But also that lowering the beam rep. rate stability degrades (e.g. 1 MHz $\rightarrow$ 200kHz)
- Transient effect in cavities (filling/field variation)
- Long. Range Wakefields (pulsed but also in CW e.g. due to varying charge)
- Do we measure voltage that contributed to beam acceleration correctly?
E.g. 7/9pi mode already contributes, imperfection of probe pickup, geometry
- Are chicane dipole PS stable enough (+ EMI may contribute)
- ...