

Calculating Losses in AC Accelerator Magnets



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Overview



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- Finite-element simulation
- Losses in accelerator magnets
- Modelling and simulation challenges
- Homogenisation of coils
- Homogenisation of lamination stacks

Finite-element simulation

$$\nabla \times (\nu \nabla \times \vec{A}) + \sigma \frac{\partial \vec{A}}{\partial t} = \vec{J}_s$$

$\vec{J}_s$ applied current density (coils)

ν reluctivity

σ conductivity

$\vec{A}$ magnetic vector potential

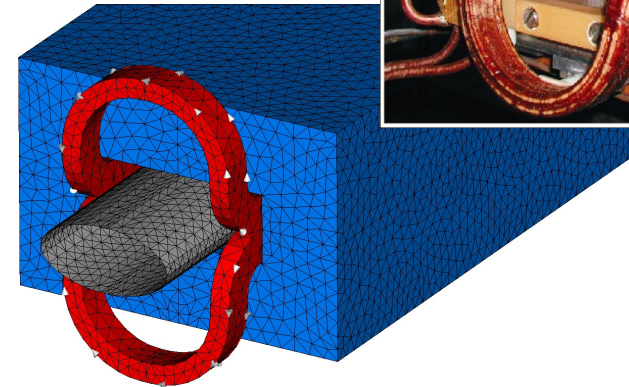
$\vec{B} = \nabla \times \vec{A}$ magnetic flux density

$\vec{J}_e = -\sigma \frac{\partial \vec{A}}{\partial t}$ eddy-current density

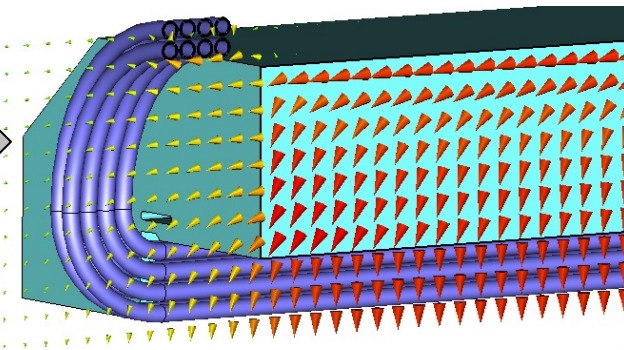
$p = \frac{1}{\sigma} |\vec{J}_s + \vec{J}_e|^2$ loss density

$\vec{J}_e \rightarrow \vec{A}_e \rightarrow \vec{B}_e$ parasitic field

mesher



FE solver



2nd order FEs, multigrid+CG, implicit Runge Kutta

Losses in Accelerator Magnets



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ramped/AC magnets

ramped magnets : increase during acceleration
AC magnets : orbit corrections

losses in ramped/AC magnets

coil Joule losses
coil eddy-current losses
yoke eddy-current losses
yoke hysteresis losses

prevention

coil many thin wires, twisting, transposition
yoke many thin laminations

appropriate cooling

Modelling and Simulation Challenges

time dependence

nonlinear material

steep ramping

→ adaptive time stepping needed

many geometric details (prevention of losses)

homogenisation unavoidable

coil

conductor model

lamination

bulk model for lamination stack

numerical accuracy

looking for a secondary effect → higher accuracy needed

spatial scale, related to skin depth → large FE mesh

temporal scale, related to ramping → many time steps

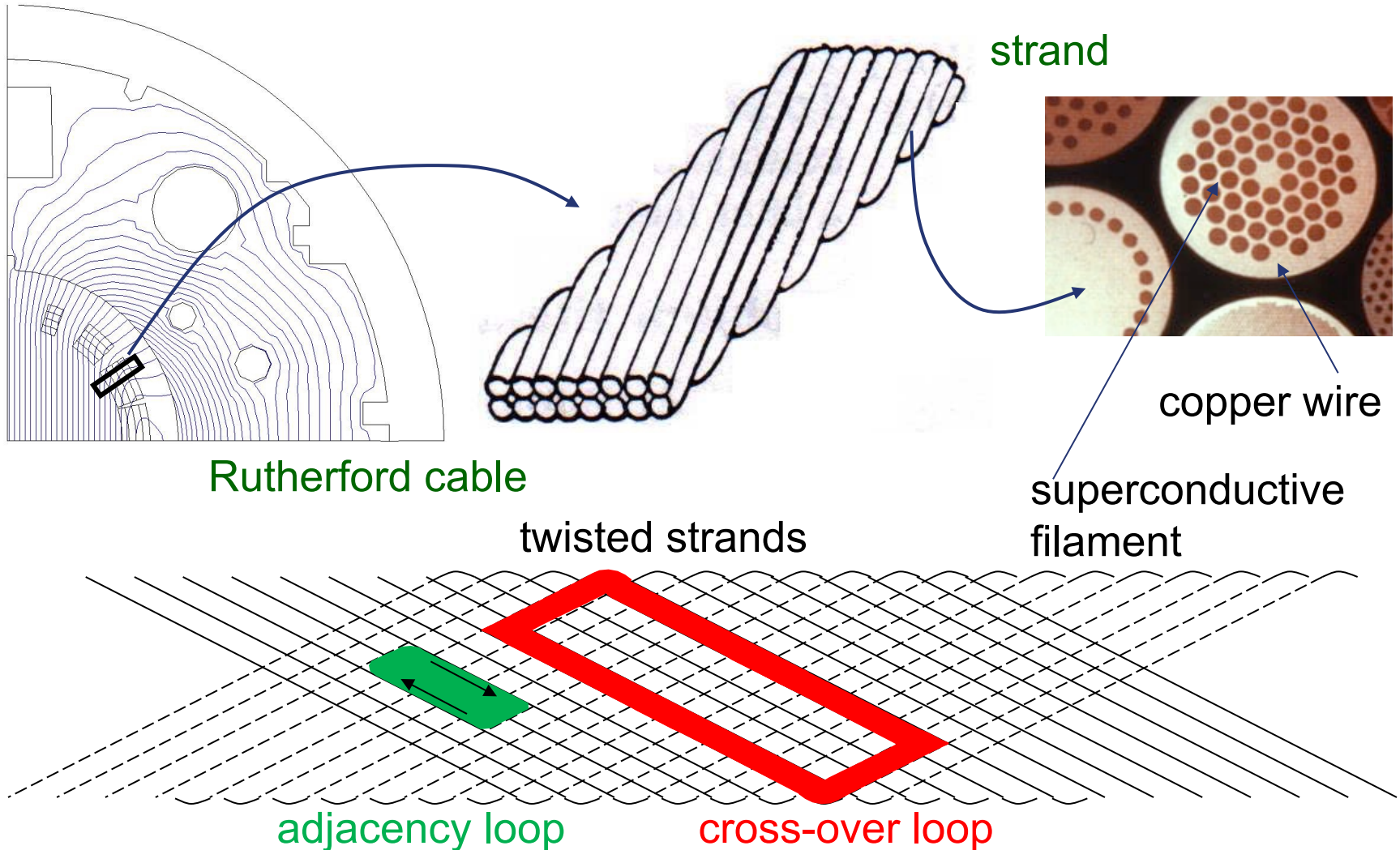
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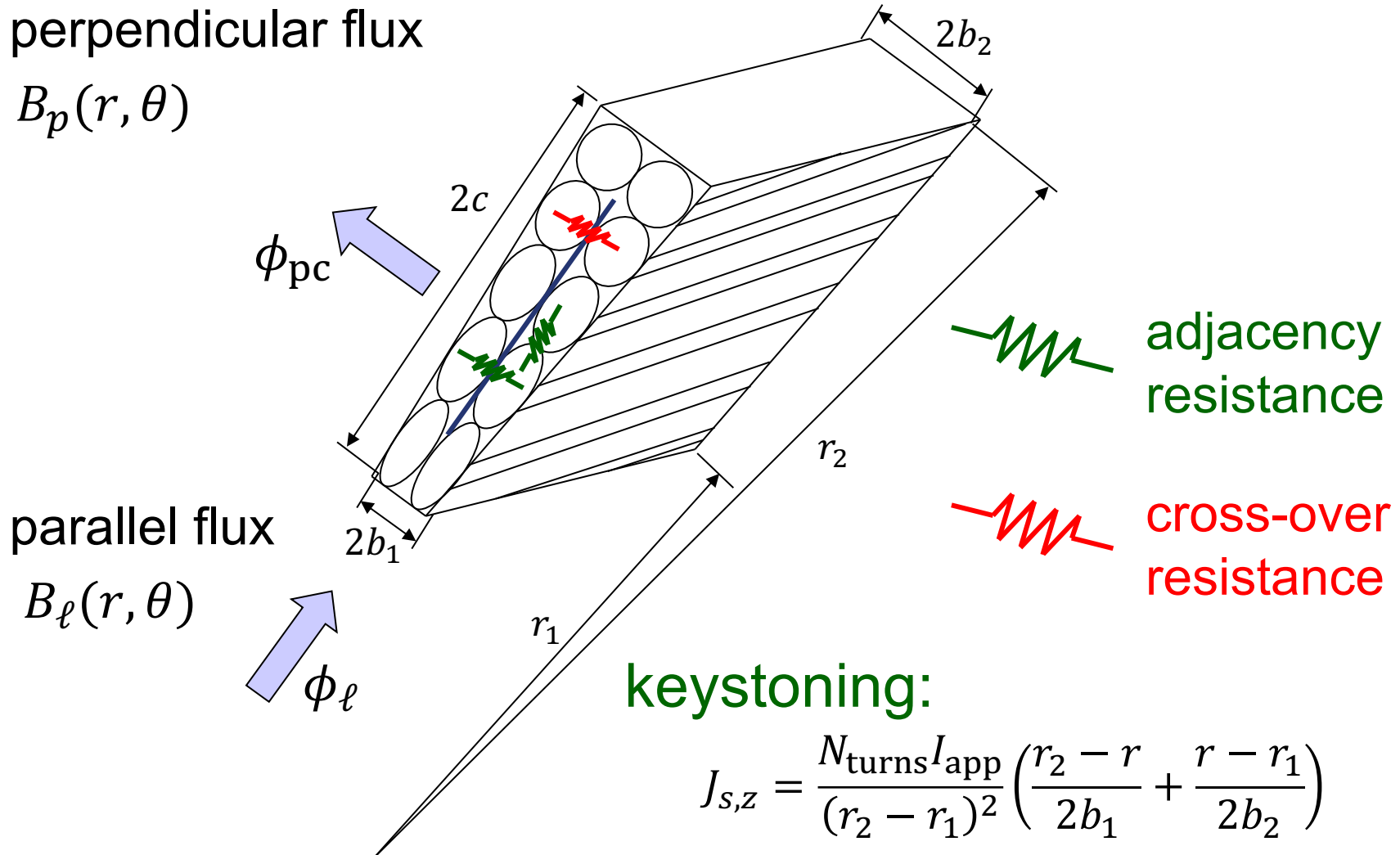
Rutherford Cable (1)



Rutherford Cable (2)

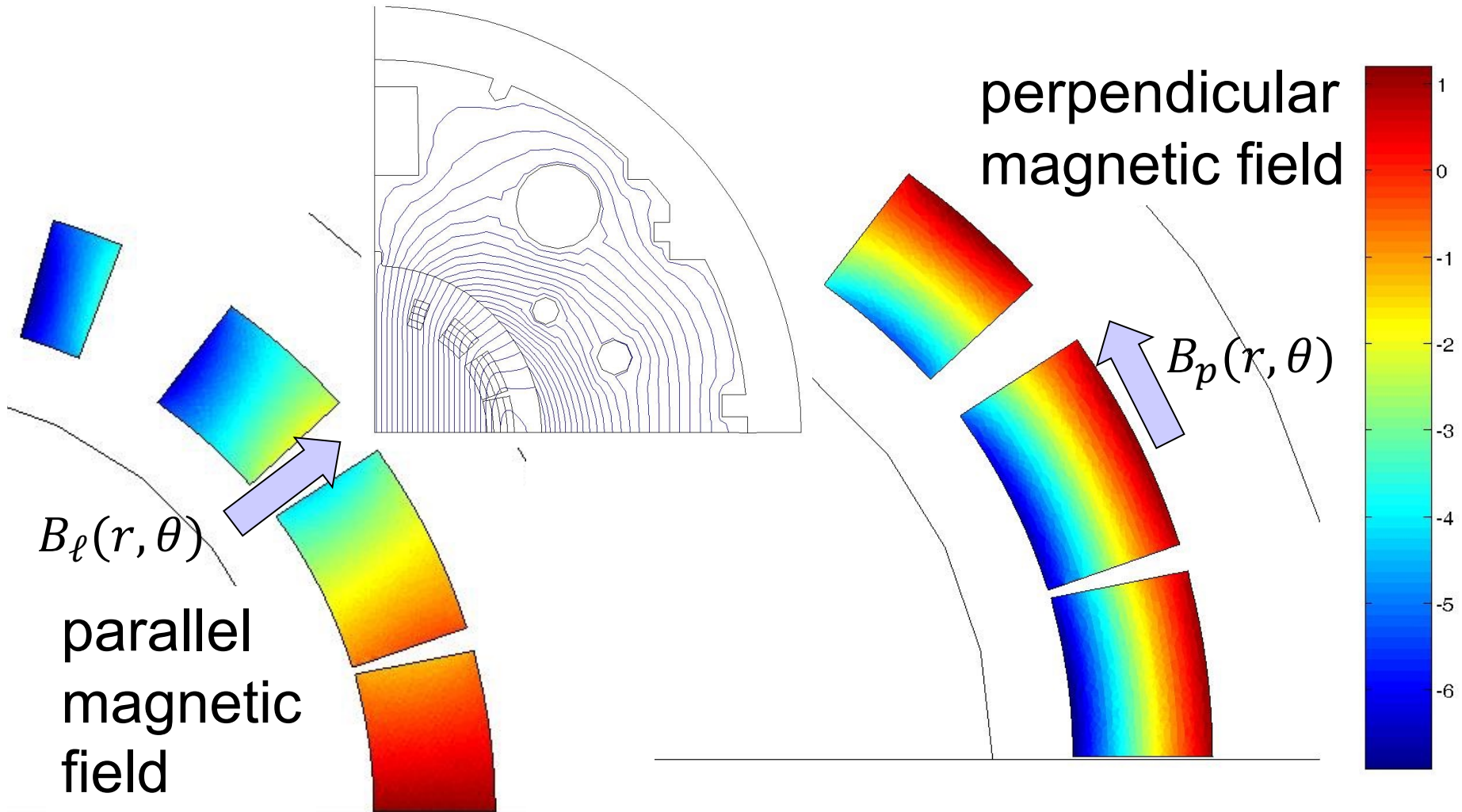
perpendicular flux

$$B_p(r, \theta)$$

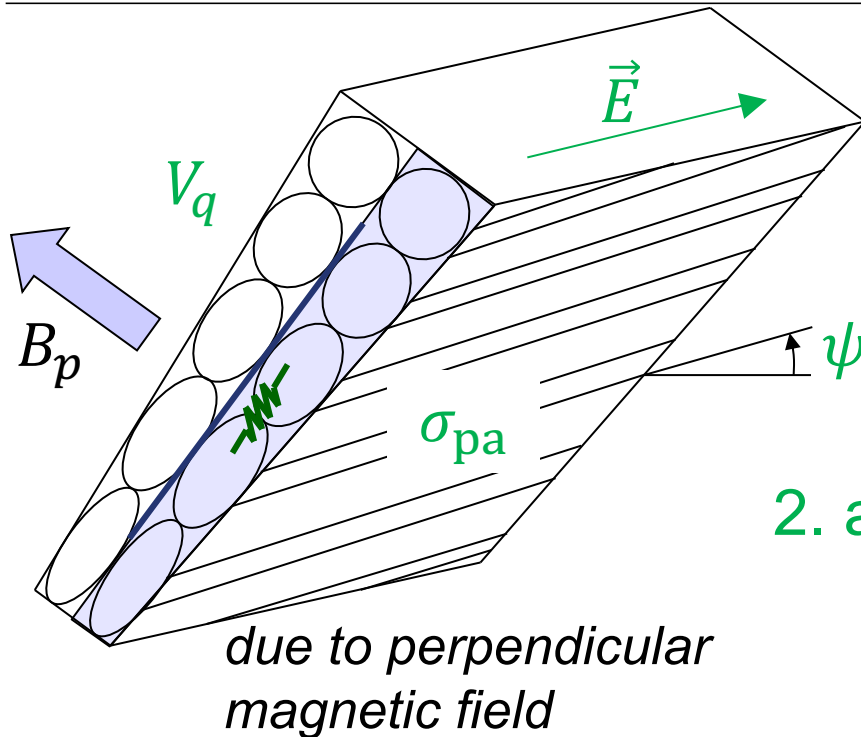


$$J_{s,z} = \frac{N_{\text{turns}} I_{\text{app}}}{(r_2 - r_1)^2} \left(\frac{r_2 - r}{2b_1} + \frac{r - r_1}{2b_2} \right)$$

Magnetic Flux Density



Adjacency Eddy Currents (1)



1. additional discretisation for unknown electric field

$$\vec{E}_{pa}(\vec{r}, t) = \sum_q u_q(t) \vec{\xi}_q(\vec{r})$$

2. adjacency eddy current density :

$$\vec{J}_{pa} = \sigma_{pa} \left(\vec{E}_{pa} - \frac{\partial \vec{A}}{\partial t} \right)$$

3. netto current through $V_q = 0$

$$I_{pa,q} = \int_{V_q} \vec{J}_{pa} \cdot \vec{\xi}_q(\vec{r}) dV' = 0 \quad \left. \vphantom{\int_{V_q}} \right\} \text{additional constraint !}$$

Adjacency Eddy Currents (2)

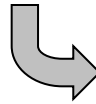


*additional load term for
magnetic FE model*

$$g_{pa} = M_{pa} \frac{d\hat{a}}{dt} - Z_{pa} u_{pa}$$

additional constraint

$$-Z_{pa}^T \frac{d\hat{a}}{dt} + G_{pa} u_{pa} = 0$$



degrees of freedom for u_{pa}

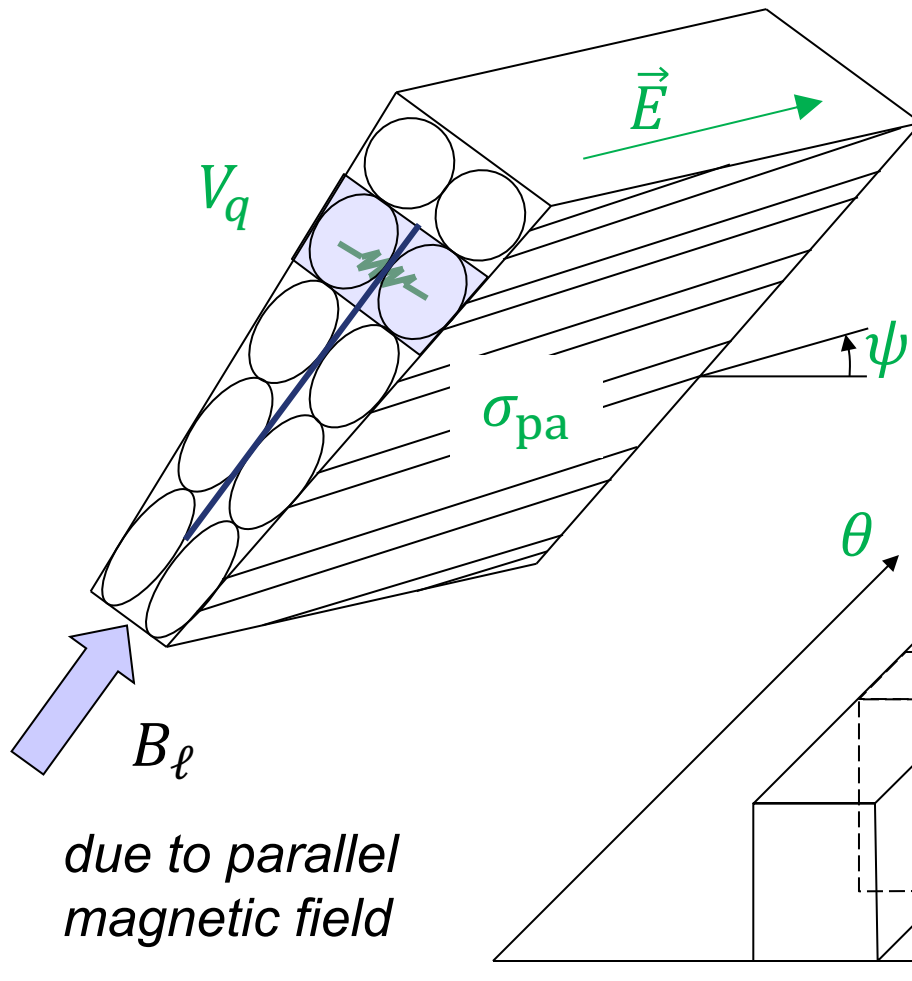
$$\begin{bmatrix} M_{pa} & 0 \\ Z_{pa}^T & 0 \end{bmatrix} \frac{d}{dt} \begin{bmatrix} \hat{a} \\ u_{pa} \end{bmatrix} + \begin{bmatrix} K & Z_{pa} \\ 0 & G_{pa} \end{bmatrix} \begin{bmatrix} \hat{a} \\ u_{pa} \end{bmatrix} = \begin{bmatrix} f \\ 0 \end{bmatrix}$$

$$M_{pa,ij} = \int_V \sigma_{pa} \vec{w}_i \cdot \vec{w}_j dV'$$

$$Z_{pa,iq} = \int_V \sigma_{pa} \vec{w}_i \cdot \vec{\xi}_q dV'$$

$$G_{pa,pq} = \int_V \sigma_{pa} \vec{\xi}_p \cdot \vec{\xi}_q dV'$$

Adjacency Eddy Currents (3)



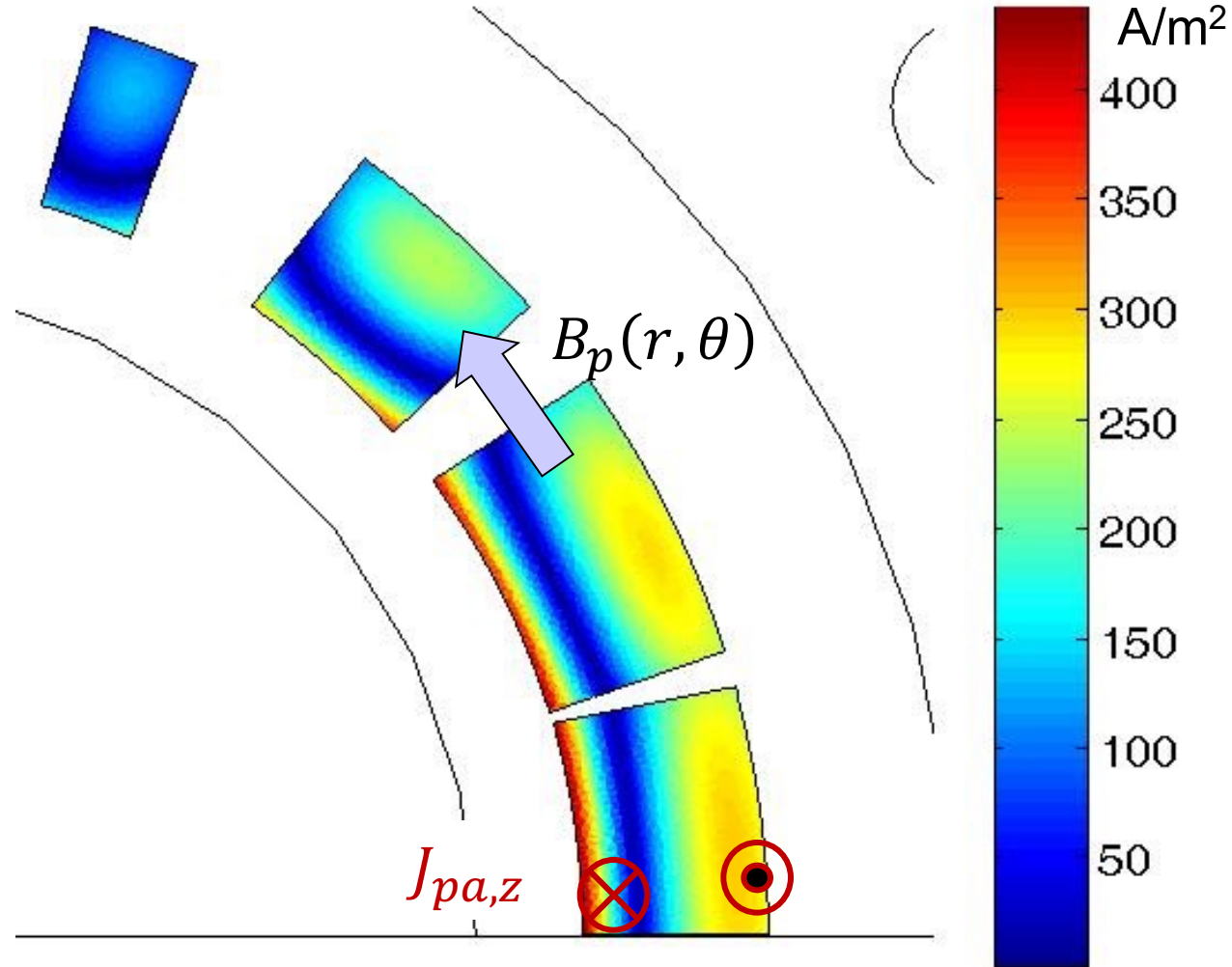
shape functions $\vec{\xi}_q(\vec{r})$ are related (but not necessarily equal) to the zones of current redistribution

$$\vec{\xi}_q(\vec{r}) = \frac{\vec{e}_z}{\ell_z} \text{ in } V_q$$

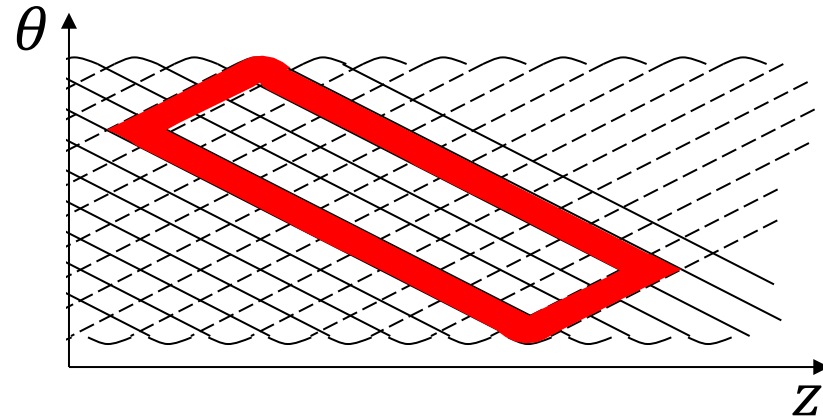
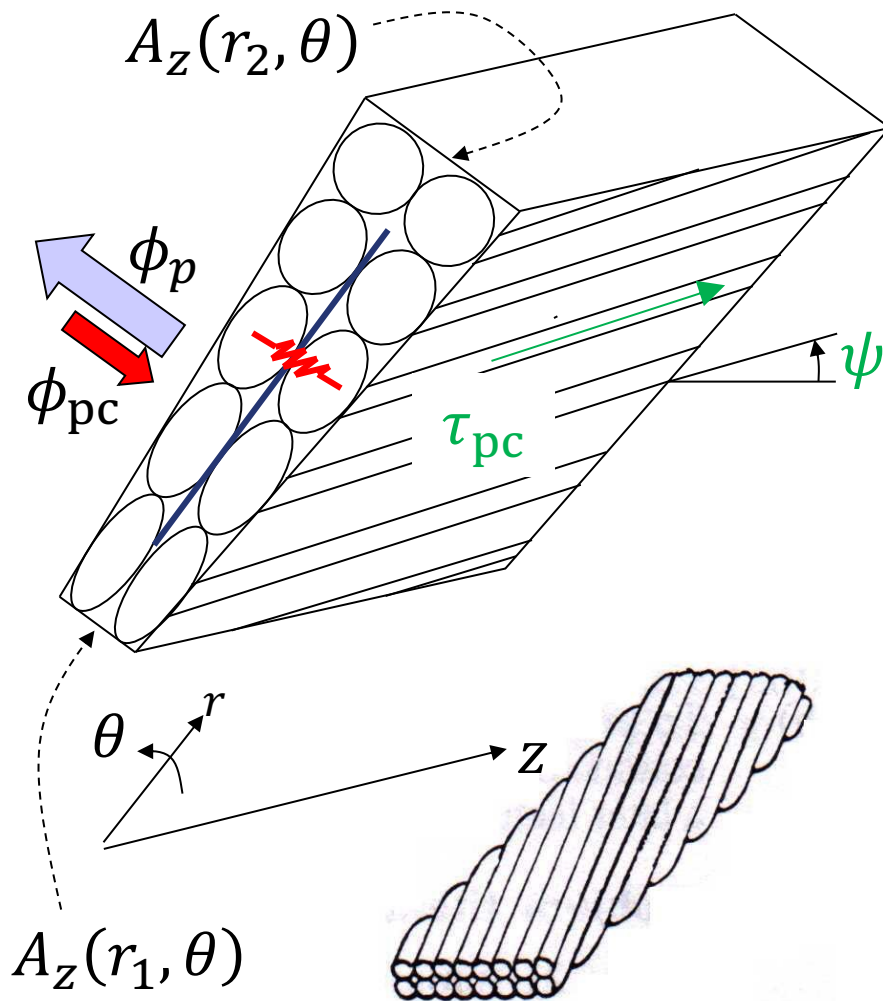
$$\vec{\xi}_q(\vec{r}) = 0 \text{ outside } V_q$$

Adjacency Eddy Currents (4)

adjacency eddy
currents due to
perpendicular
magnetic field



Cross-over Eddy Currents (1)



1. coupled flux

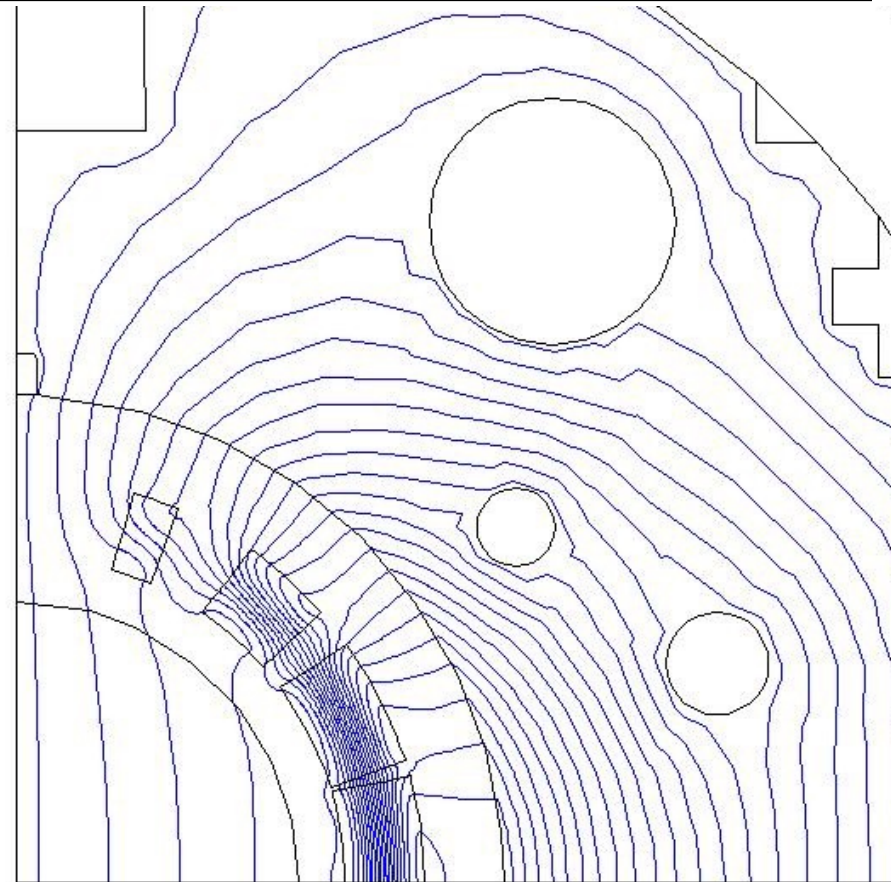
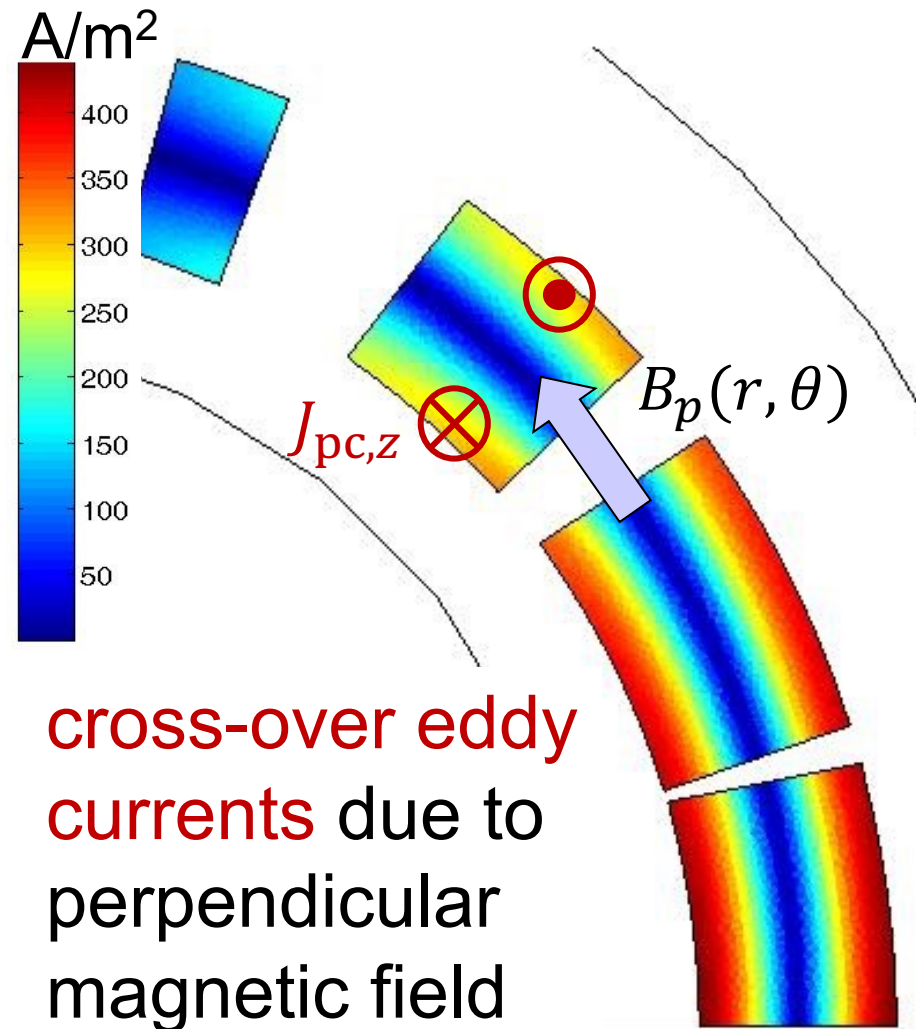
$$\phi_p(\theta) = \ell_z (A_z(r_2, \theta) - A_z(r_1, \theta))$$

2. magnetisation

$$\phi_{pc}(\theta) = \tau_{pc} \frac{\partial \phi_p(\theta)}{\partial t}$$

time constant

Cross-over Eddy Currents (2)



cross-over magnetisation

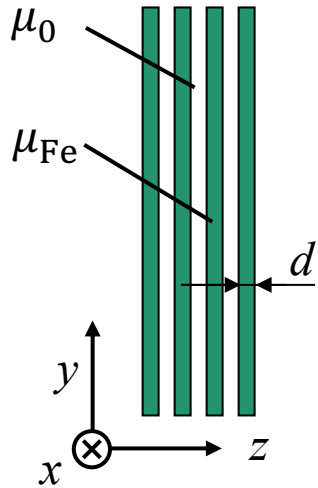
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Homogenisation: Lamination Stacks



$$\nabla \times (\vec{v} \nabla \times \vec{A}) + \nabla \times \left(\vec{\tau} \nabla \times \frac{\partial \vec{A}}{\partial t} \right) + \vec{\sigma} \frac{\partial \vec{A}}{\partial t} = \vec{J}_s$$

homogenisation with fill factor γ

reluctivity

$$\vec{v} = \left(\frac{\gamma}{\mu_{\text{Fe}}} + \frac{1-\gamma}{\mu_0} \right) \begin{bmatrix} 1 & & \\ & 1 & \\ & & 0 \end{bmatrix} + \frac{1}{\gamma\mu_{\text{Fe}} + (1-\gamma)\mu_0} \begin{bmatrix} 0 & & \\ & 0 & \\ & & 1 \end{bmatrix}$$

in-plane flux

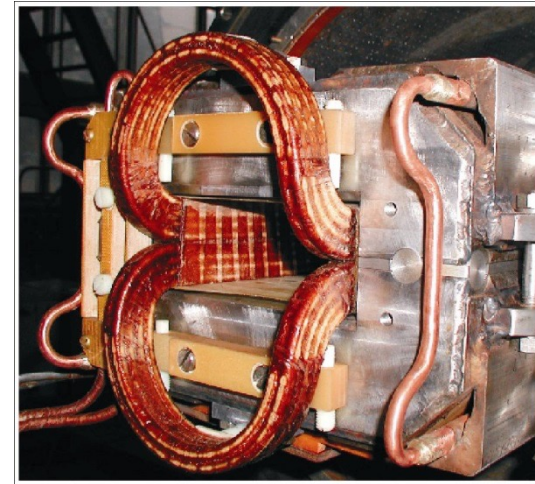
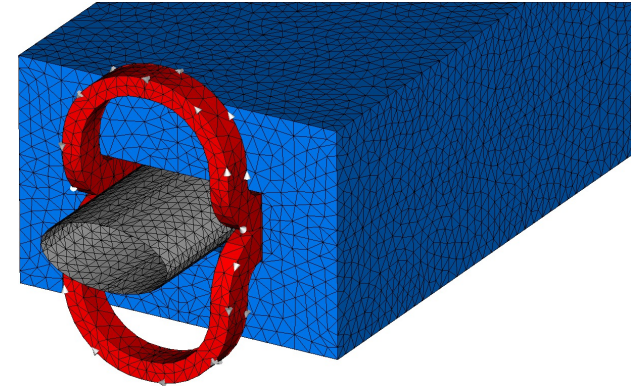
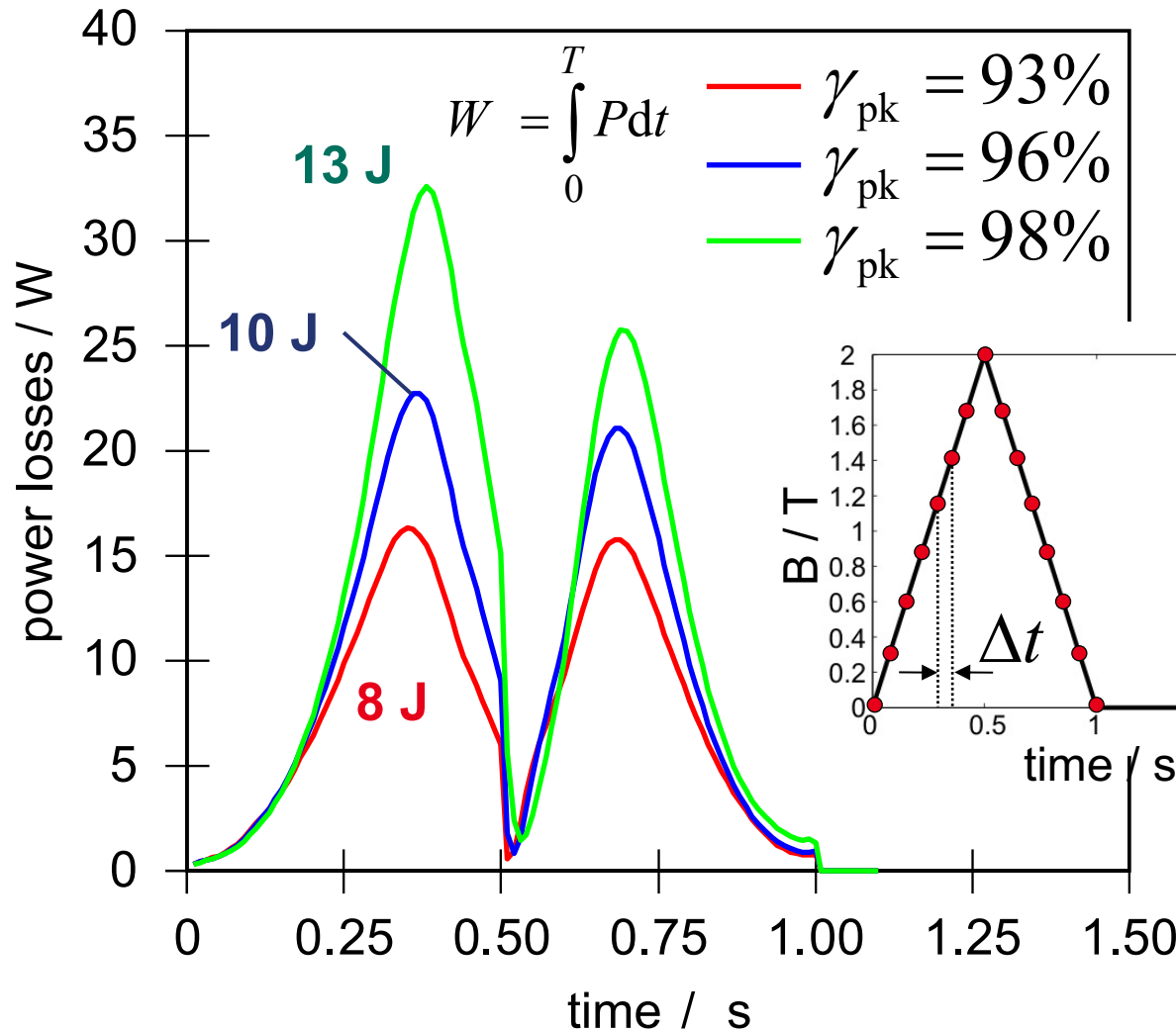
$$\vec{\tau} = \frac{1}{2} \gamma \sigma d^2 \begin{bmatrix} 1 & & \\ & 1 & \\ & & 0 \end{bmatrix}$$

perpendicular flux

$$\vec{\sigma} = \gamma \sigma \begin{bmatrix} 1 & & \\ & 1 & \\ & & 0 \end{bmatrix}$$

S. Koch et al., 2008
J. Gyselinck et al. 1999

Example: FAIR SIS100 Magnet

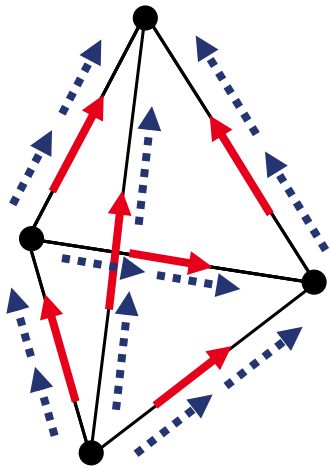


+ S. Koch, J. Trommler

Example: FAIR SIS100 Magnet

relative error with
respect to
reference solution

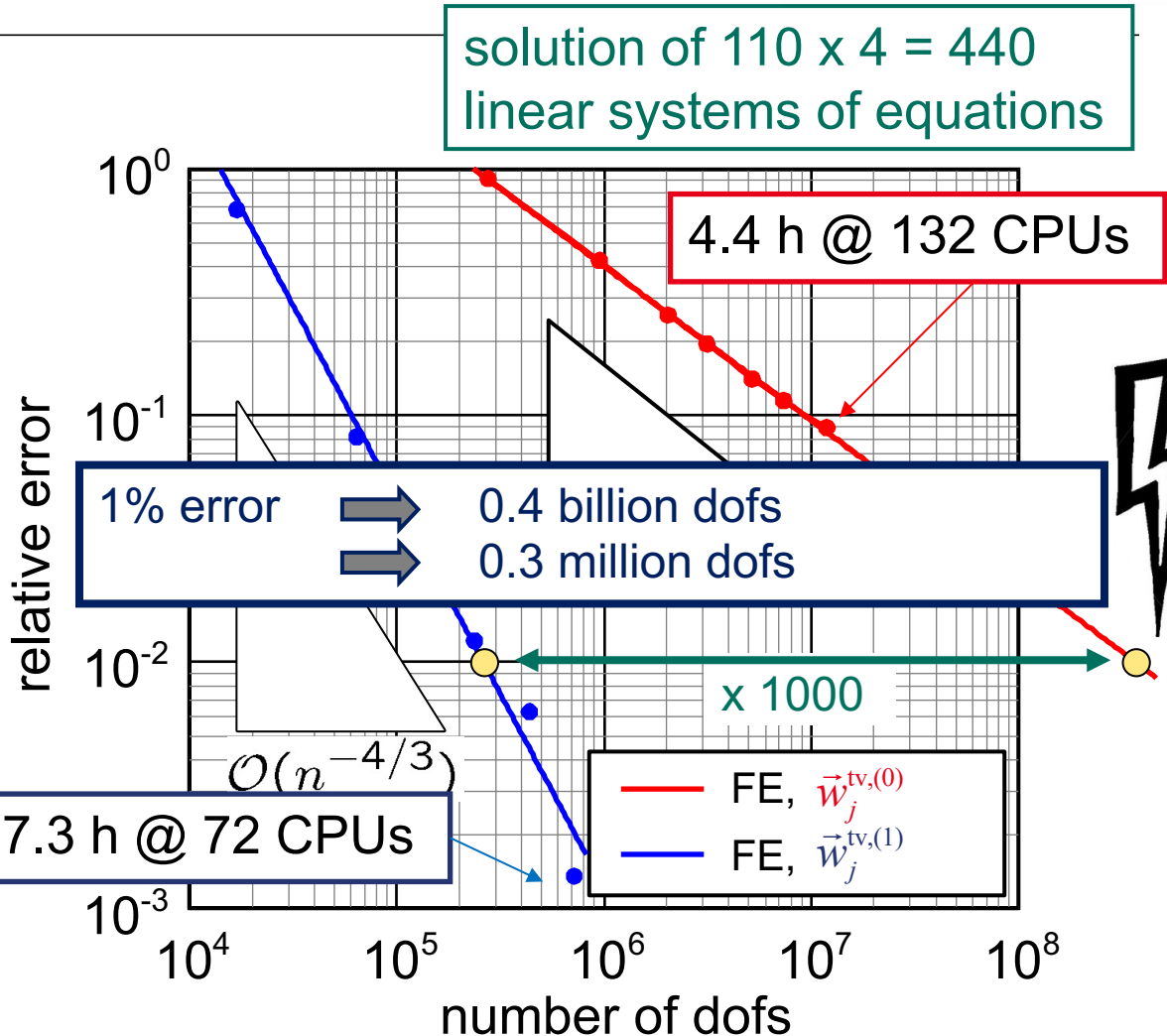
degrees of freedom:



+ 2 per face

$$\vec{w}_j^{tv,(0)}$$

$$\vec{w}_j^{tv,(1)}$$



+ S. Koch, J. Trommler

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